

Thermomechanical Reliability of Microelectronics

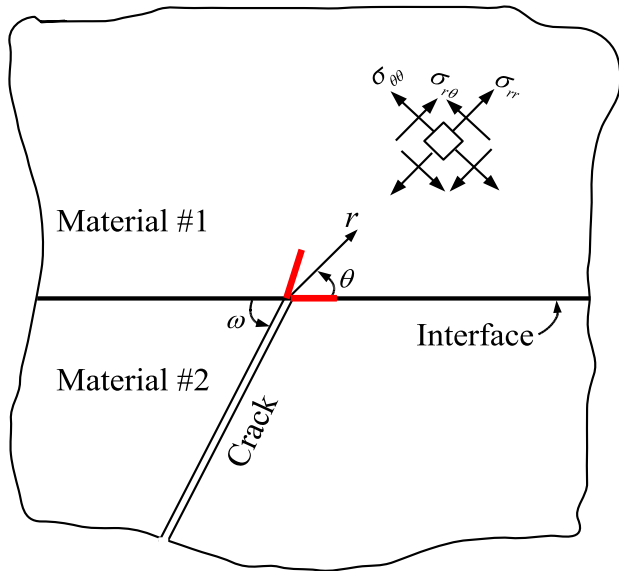
Zhen Zhang

School of Engineering and Applied Sciences

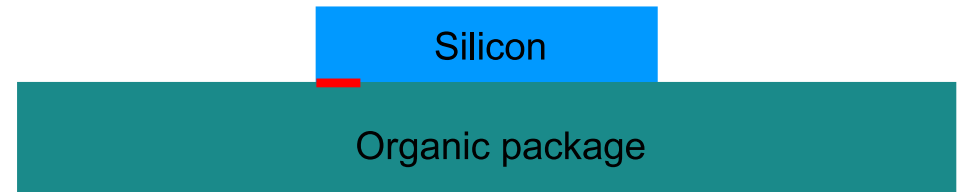
Advisor: Zhigang Suo

Harvard University SRC
MRSEC

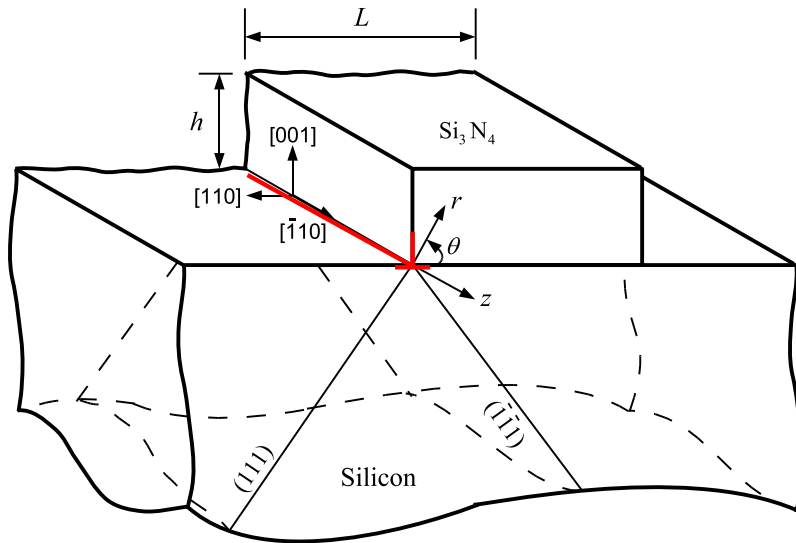
Topics



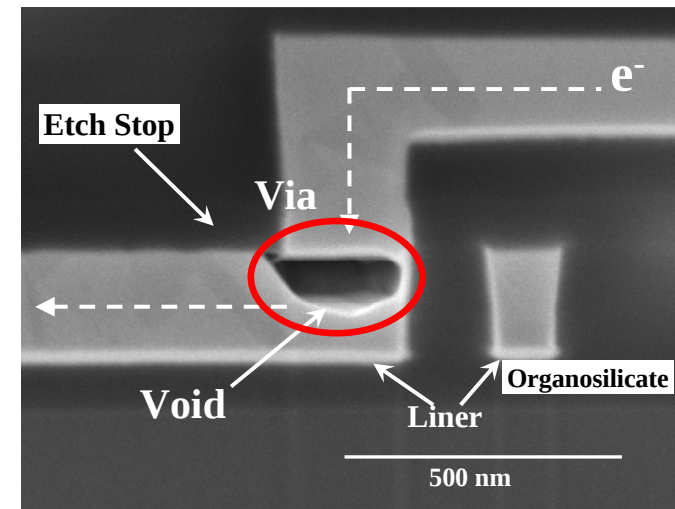
Crack penetration or debonding



Interfacial delamination



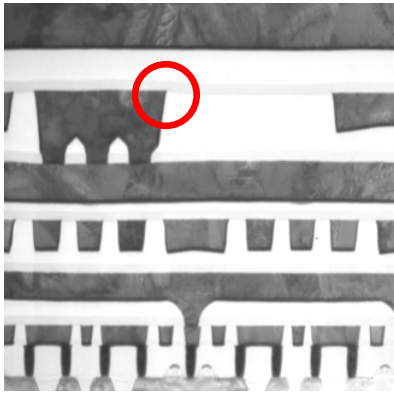
Dislocation injection



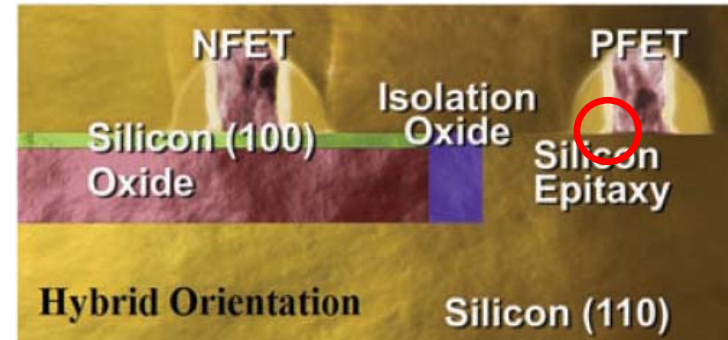
Voiding and electromigration



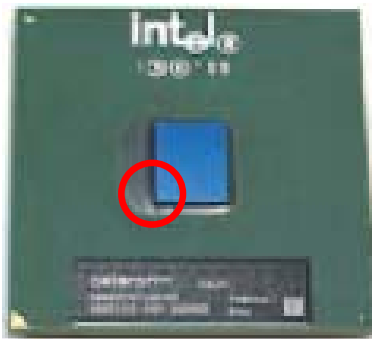
Diverse Materials & Sharp Features



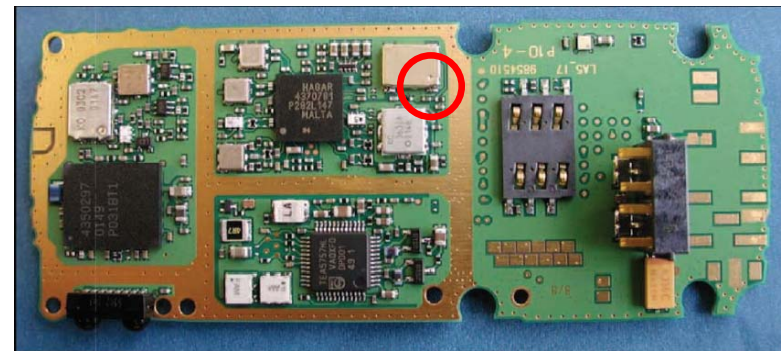
Intel 90 nm interconnect



Ieong et al, Science **306**(2004)p2057.

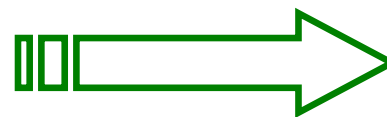


Intel Pentium III CPU



Reuss & Chalamala, MRS bulletin **28**(2003)p11.

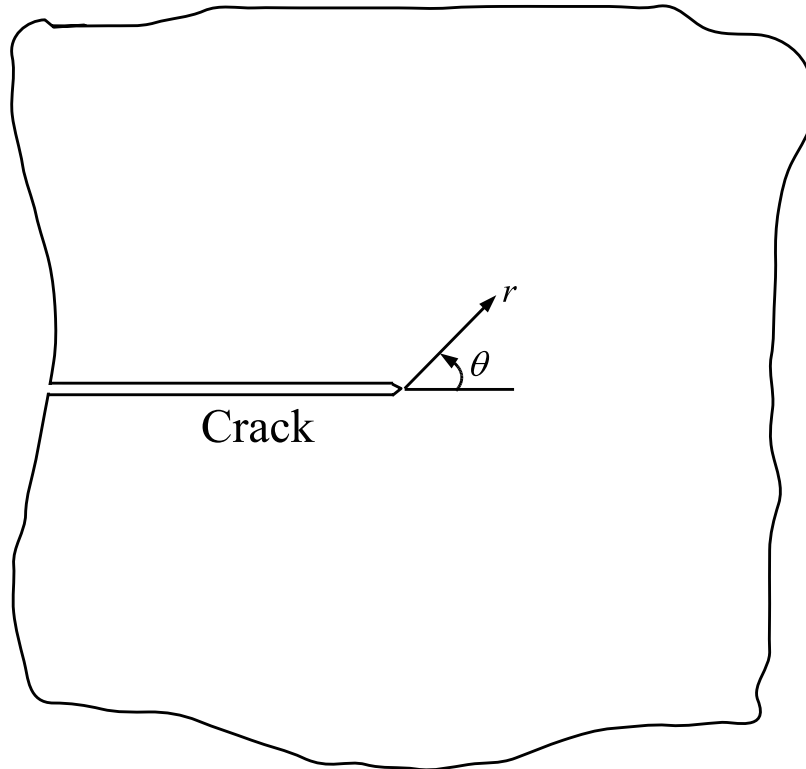
Stress concentration



Failures !

The study of the singular stress filed around the sharp features draw a lot of attention.

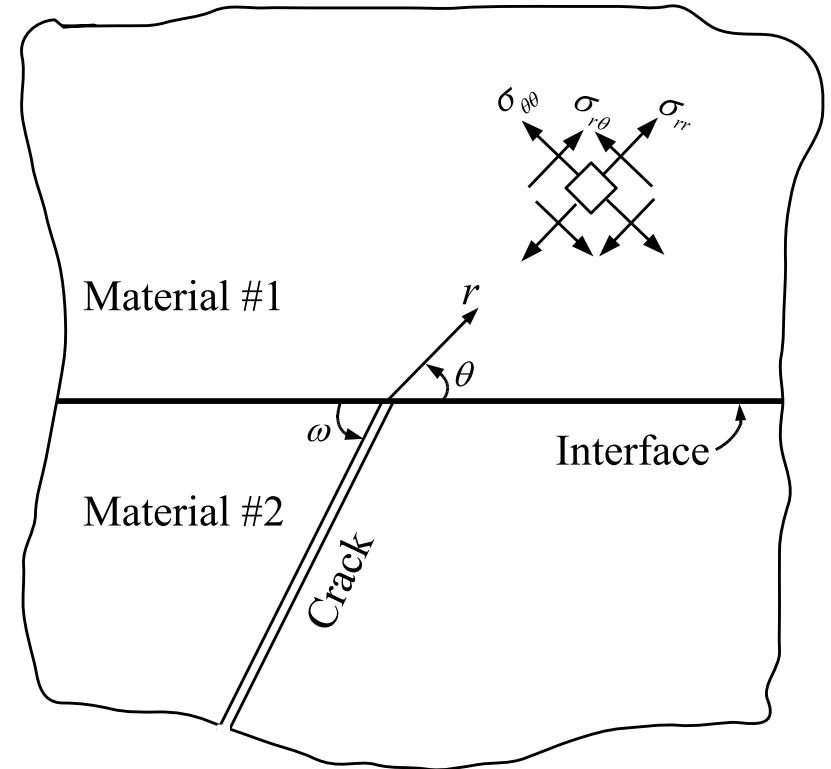
Split singularities



Homogeneous material

Two modes have the same exponents --- $1/2$

$$\sigma_{ij}(r, \theta) = \frac{K_I}{r^{1/2}} \Sigma_{ij}^I(\theta) + \frac{K_{II}}{r^{1/2}} \Sigma_{ij}^{II}(\theta)$$



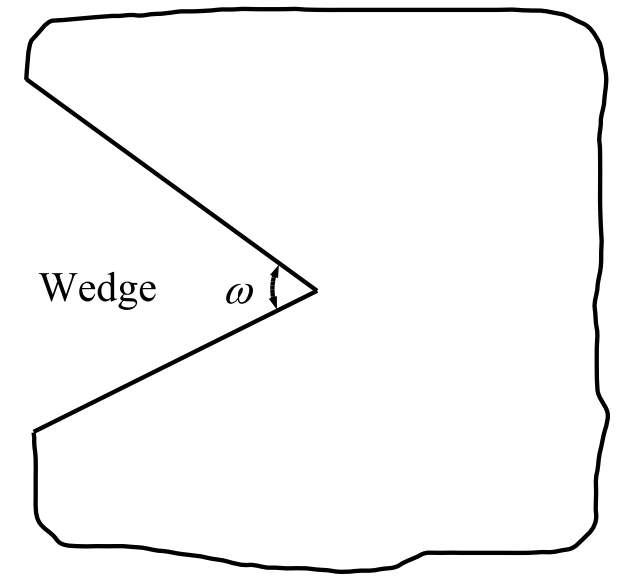
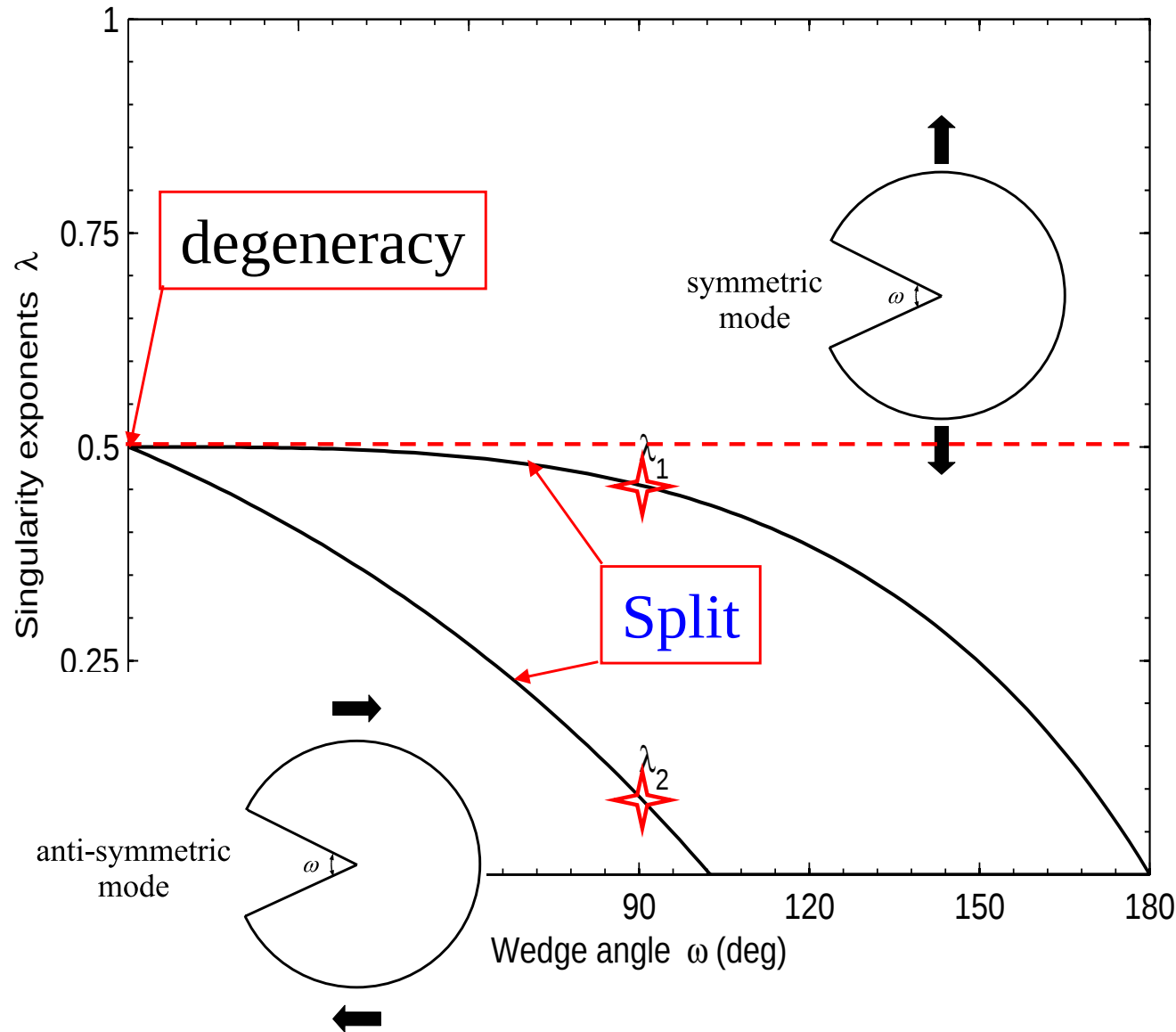
Bimaterial

Two modes have different exponents --- λ_1 and λ_2

$$\sigma_{ij}(r, \theta) = \frac{k_1}{r^{\lambda_1}} \Sigma_{ij}^1(\theta) + \frac{k_2}{r^{\lambda_2}} \Sigma_{ij}^2(\theta)$$



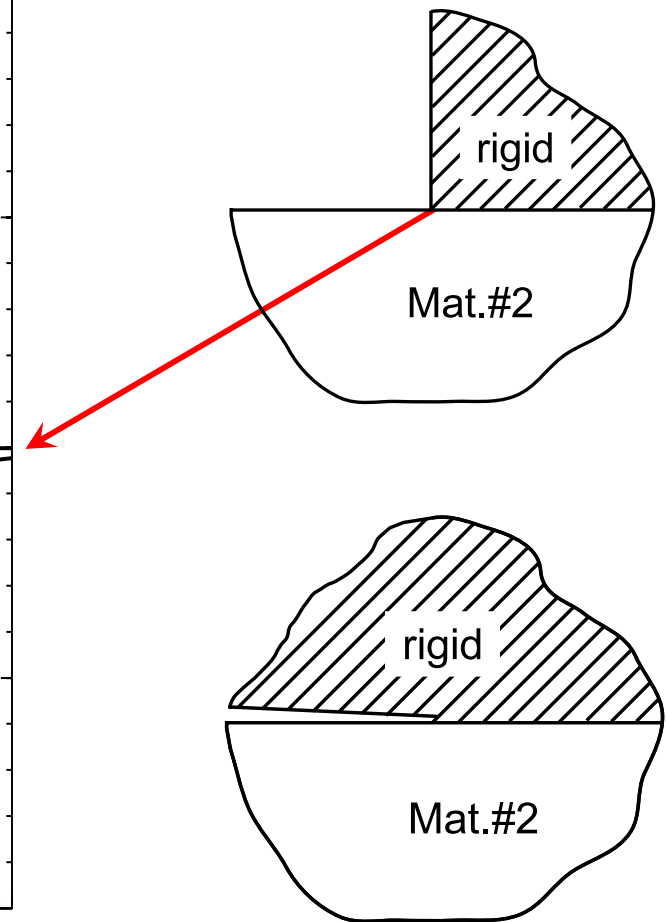
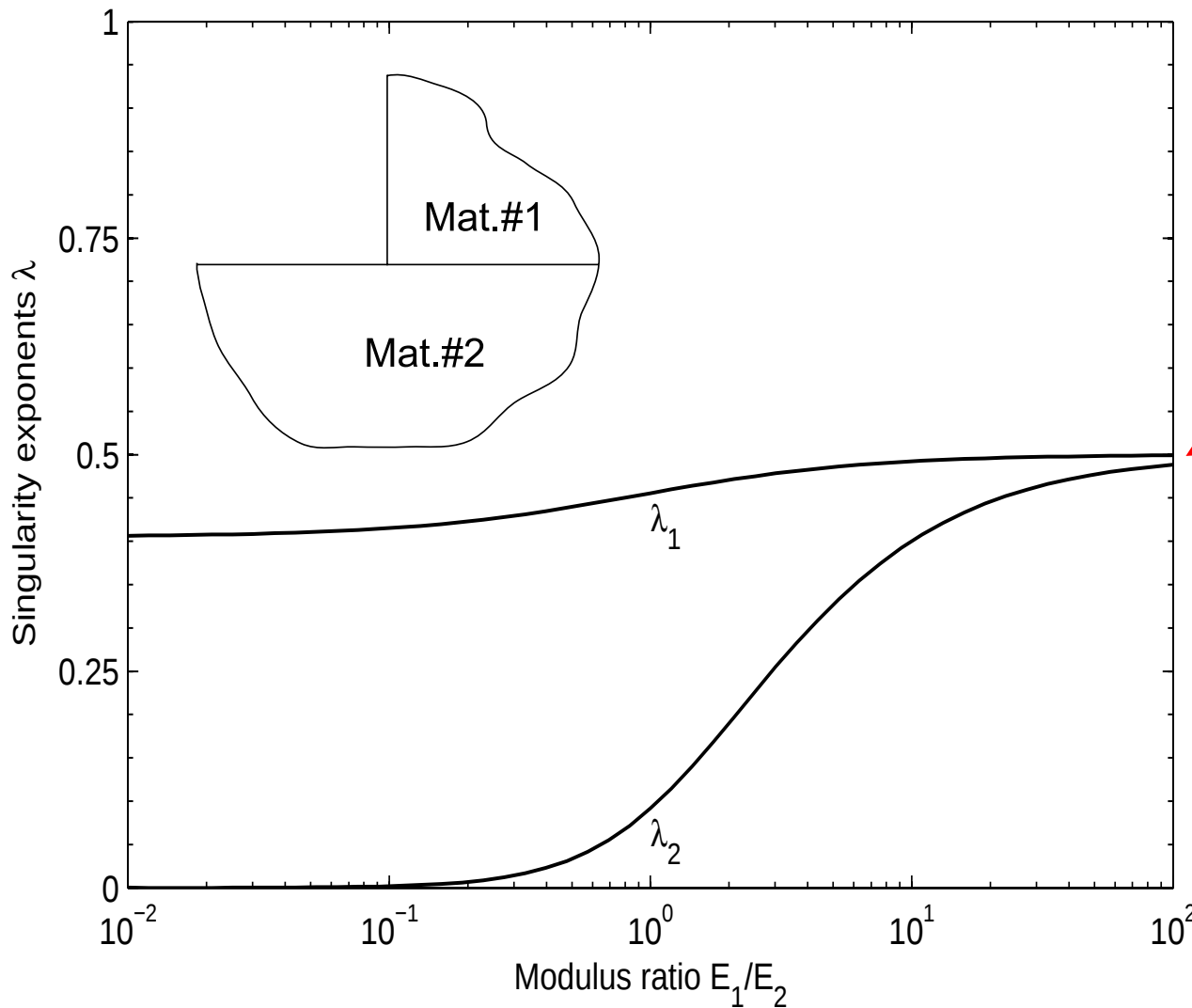
Split due to geometry



Liu, Suo and Ma, Acta mat. (1999).



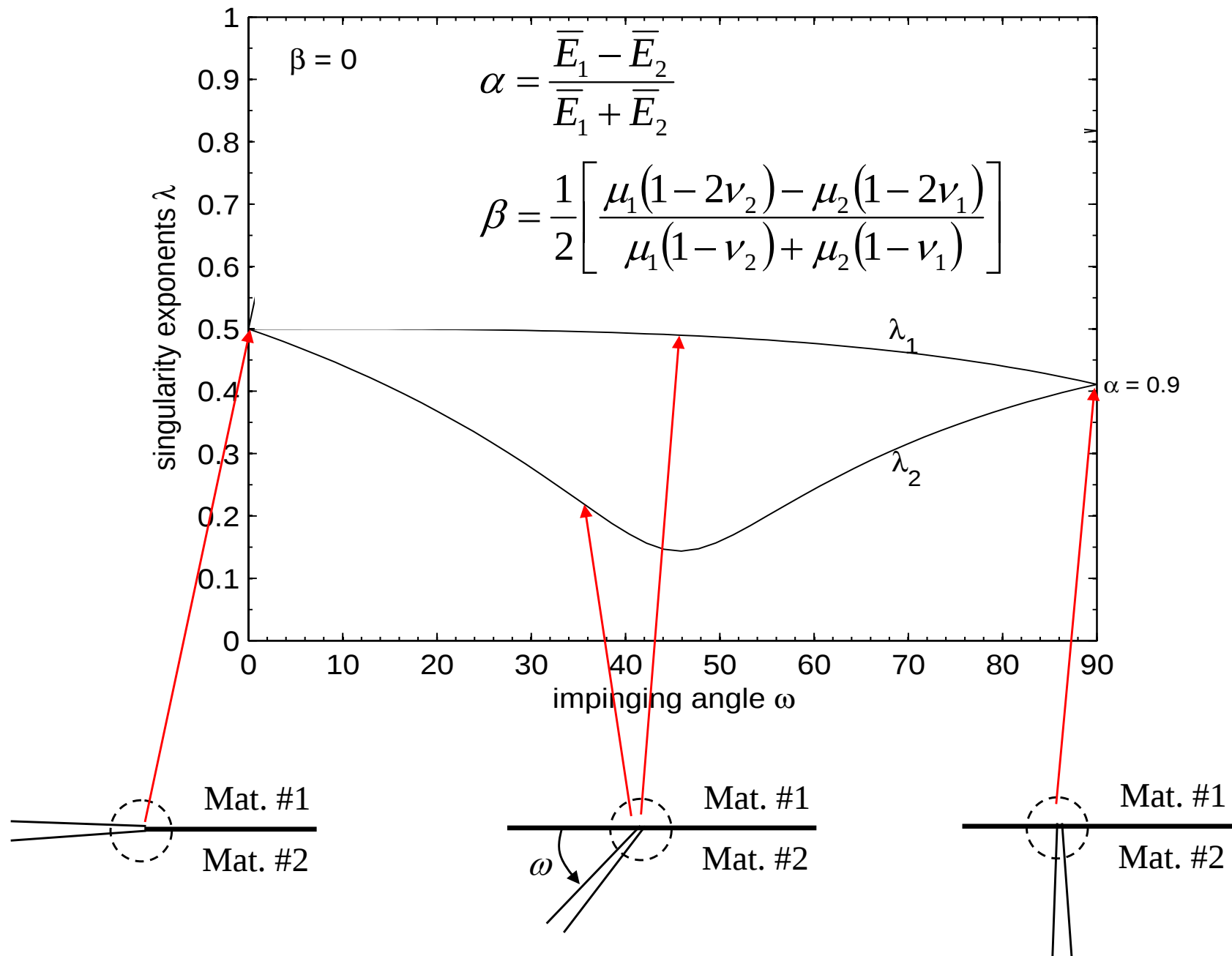
Split due to elastic mismatch



Always split, unless Mat.#1 is rigid.



Split singularities: oblique crack





Split singularities:

Rule rather than exception:

$$\sigma_{ij}(r, \theta) = \frac{k_1}{r^{\lambda_1}} \Sigma_{ij}^1(\theta) + \frac{k_2}{r^{\lambda_2}} \Sigma_{ij}^2(\theta)$$

Questions:

- Should we neglect the weaker singularity?
- How do we study the failure phenomena with consideration of weaker singularity?

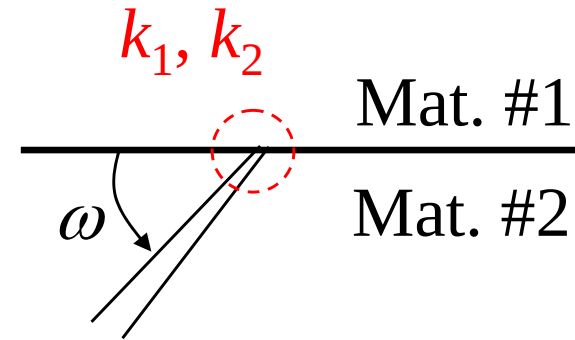


Applications and Implications: #1

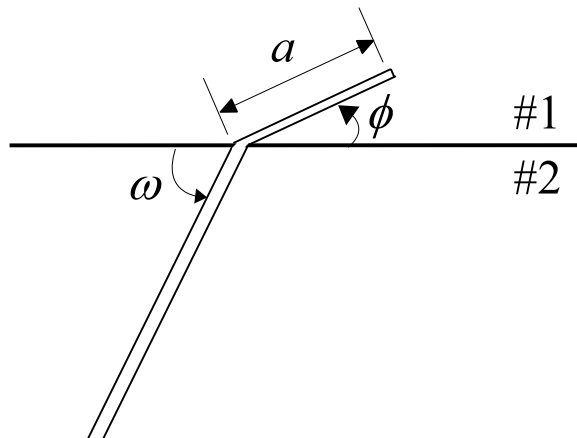
Crack Penetration or Debonding

Cracking Path Selection

A crack impinges upon an interface.
(He and Hutchinson, *IJSS*, 1989).

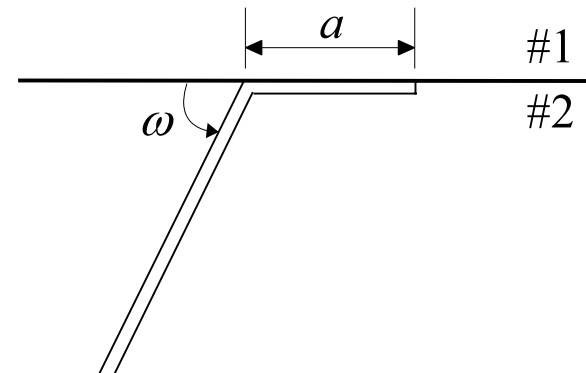


Penetration



vs.

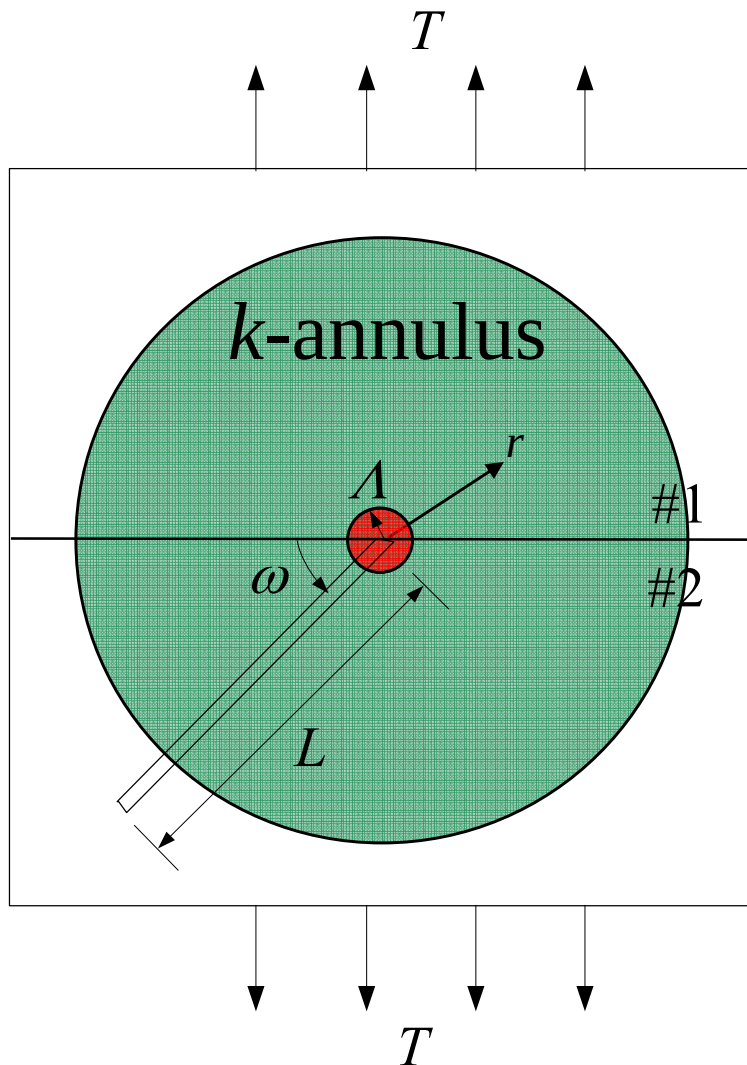
Debonding



The effect of weaker singularity has not been well studied.



Q: Should we neglect the weaker singularity?



r does NOT go to zero.

Homogeneous material:

$$\sigma_{ij}(r, \theta) = \frac{K_I}{r^{1/2}} \Sigma_{ij}^I(\theta) + \frac{K_{II}}{r^{1/2}} \Sigma_{ij}^{II}(\theta)$$

$$\text{Mode mixity} = \frac{K_{II}}{K_I}$$

Bimaterial:

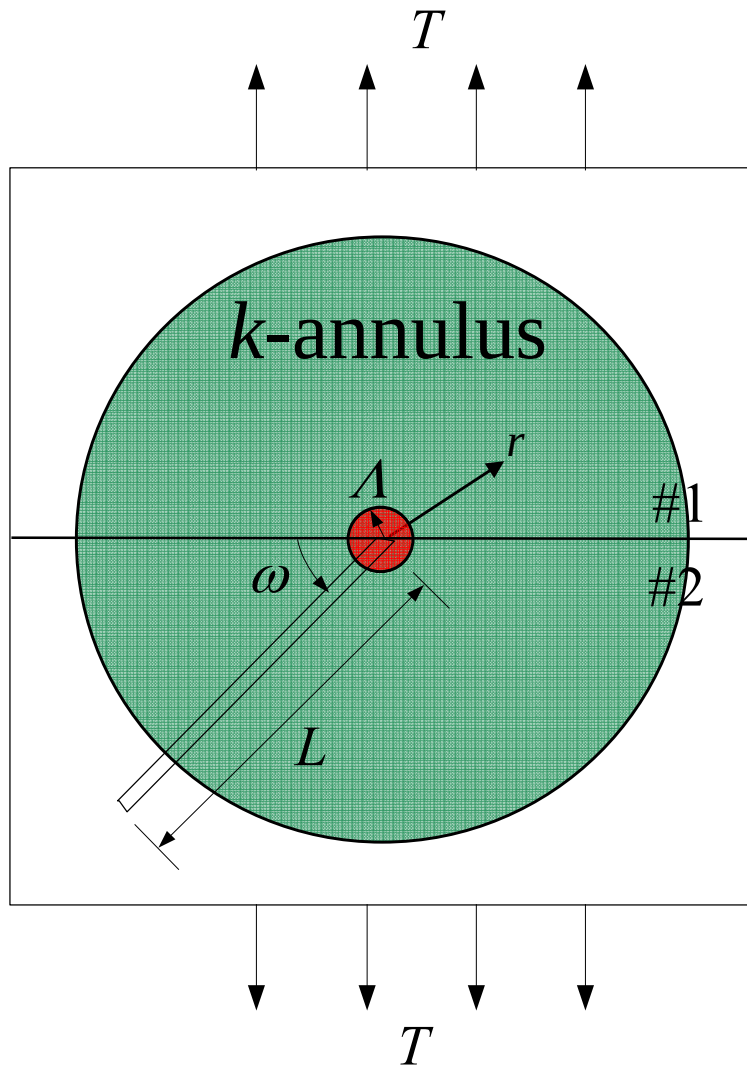
$$\sigma_{ij}(r, \theta) = \frac{k_1}{r^{\lambda_1}} \Sigma_{ij}^1(\theta) + \frac{k_2}{r^{\lambda_2}} \Sigma_{ij}^2(\theta)$$

$$\text{Stress ratio of two modes} = \frac{k_2 r^{-\lambda_2}}{k_1 r^{-\lambda_1}}$$

Selection of arbitrary length



Definition of mode mixity



$$\sigma_{ij}(r, \theta) = \frac{k_1}{r^{\lambda_1}} \Sigma_{ij}^1(\theta) + \frac{k_2}{r^{\lambda_2}} \Sigma_{ij}^2(\theta)$$

Select some length we care:

Mode mixity:

$$\eta = \frac{k_2 \Lambda^{-\lambda_2}}{k_1 \Lambda^{-\lambda_1}}$$

It measures the relative contribution of the two modes to the stress field at length scale Λ

Answer: it depends on the **magnitude** of the **mode mixity**.

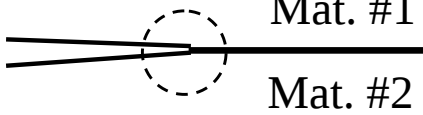


Two length scales

$$k_1 = \kappa_1 T L^{\lambda_1} \sim [\text{stress}][\text{length}]^{\lambda_1}$$

$$k_2 = \kappa_2 T L^{\lambda_2} \sim [\text{stress}][\text{length}]^{\lambda_2}$$

$$\eta = \frac{\kappa_2}{\kappa_1} \left(\frac{\Lambda}{L} \right)^{\lambda_1 - \lambda_2}$$

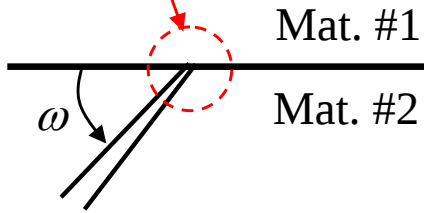


Mat. #1
Mat. #2

$$\frac{\text{Im}(K l^{i\varepsilon})}{\text{Re}(K l^{i\varepsilon})}$$

(Rice, 1988)

$\Lambda = 1 \text{ nm}$



Mat. #1
Mat. #2

ω

$L = 100 \text{ nm}$

$\eta = \frac{\kappa_2}{\kappa_1} \left(\frac{\Lambda}{L} \right)^{\lambda_1 - \lambda_2}$

0.2

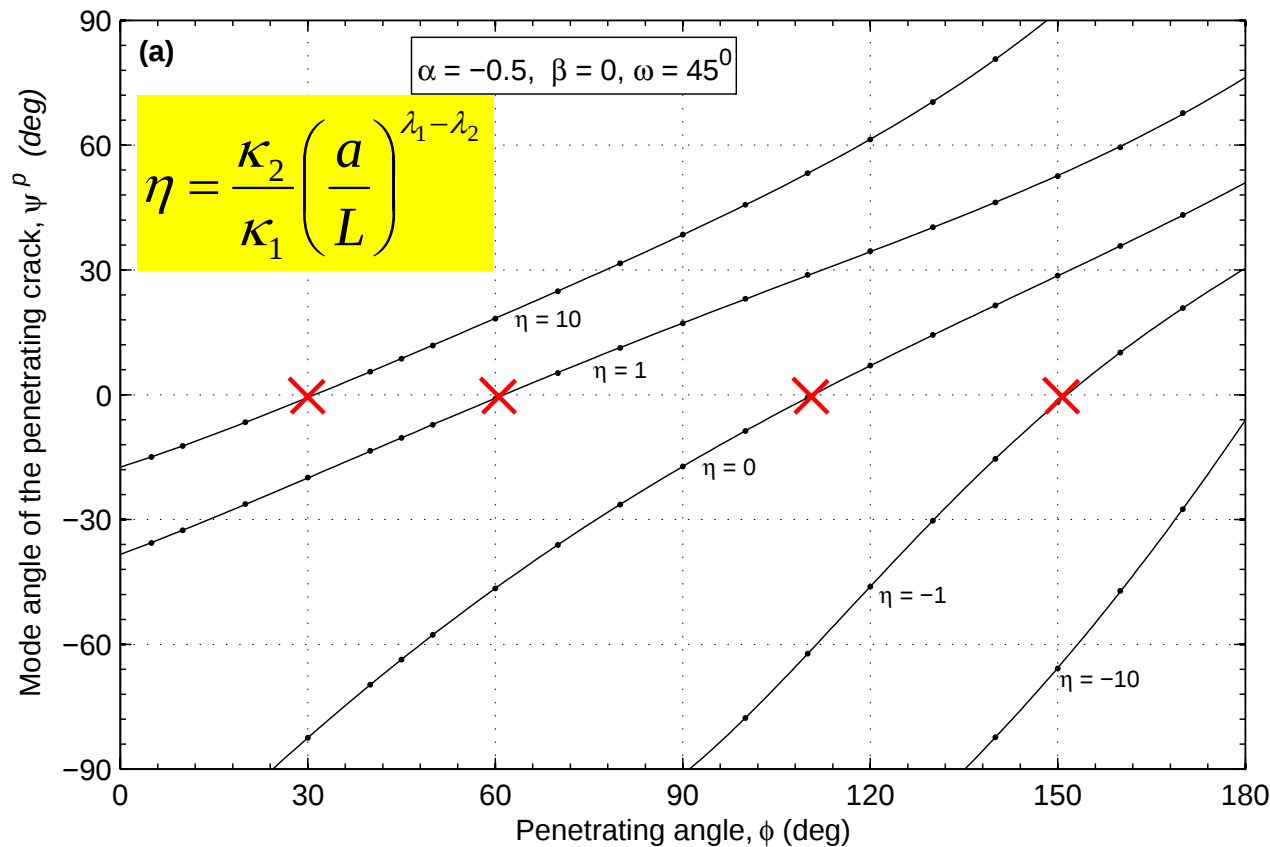
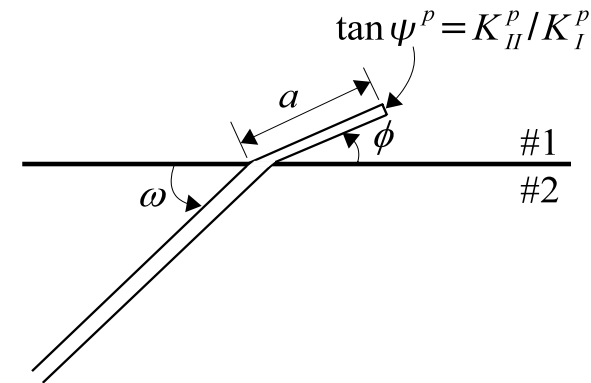
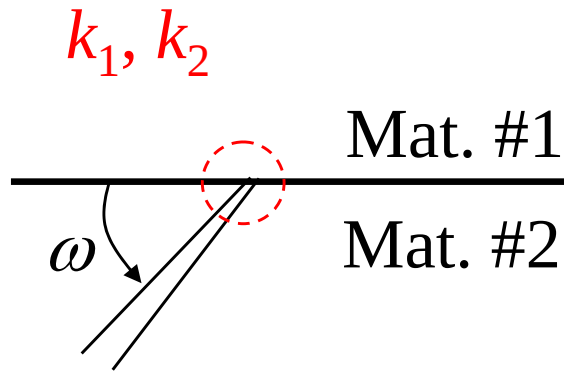
0.4

easily on the order of unity.

η is used to assess the effect of weaker singularity.



Crack penetration



$$\frac{K_I^p}{\sqrt{a}} = b_{11} \cdot \frac{k_1}{a^{\lambda_1}} + b_{12} \cdot \frac{k_2}{a^{\lambda_2}}$$

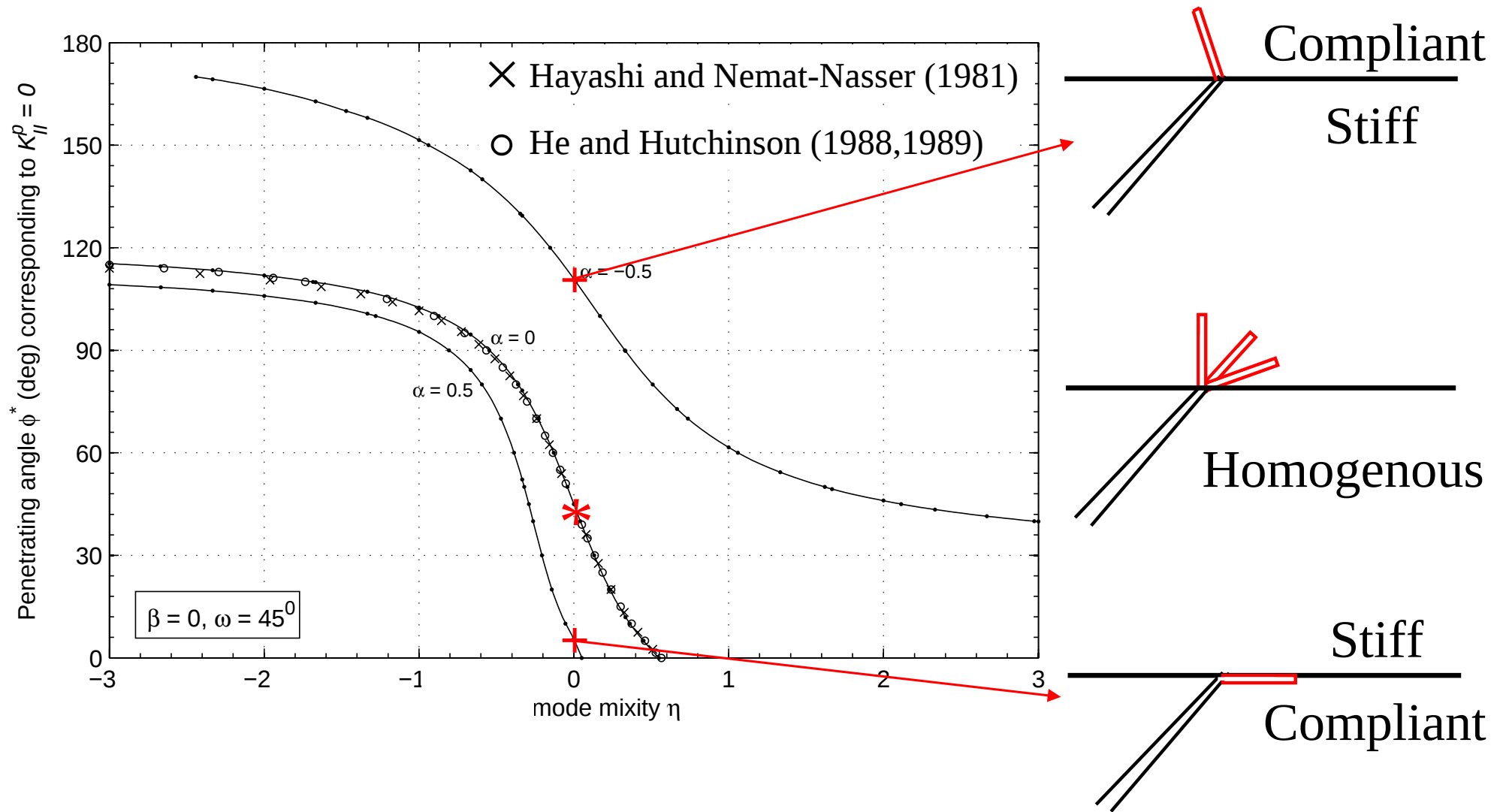
$$\frac{K_{II}^p}{\sqrt{a}} = b_{21} \cdot \frac{k_1}{a^{\lambda_1}} + b_{22} \cdot \frac{k_2}{a^{\lambda_2}}$$

Selection of penetrating angle:

$$K_{II}^p = 0$$

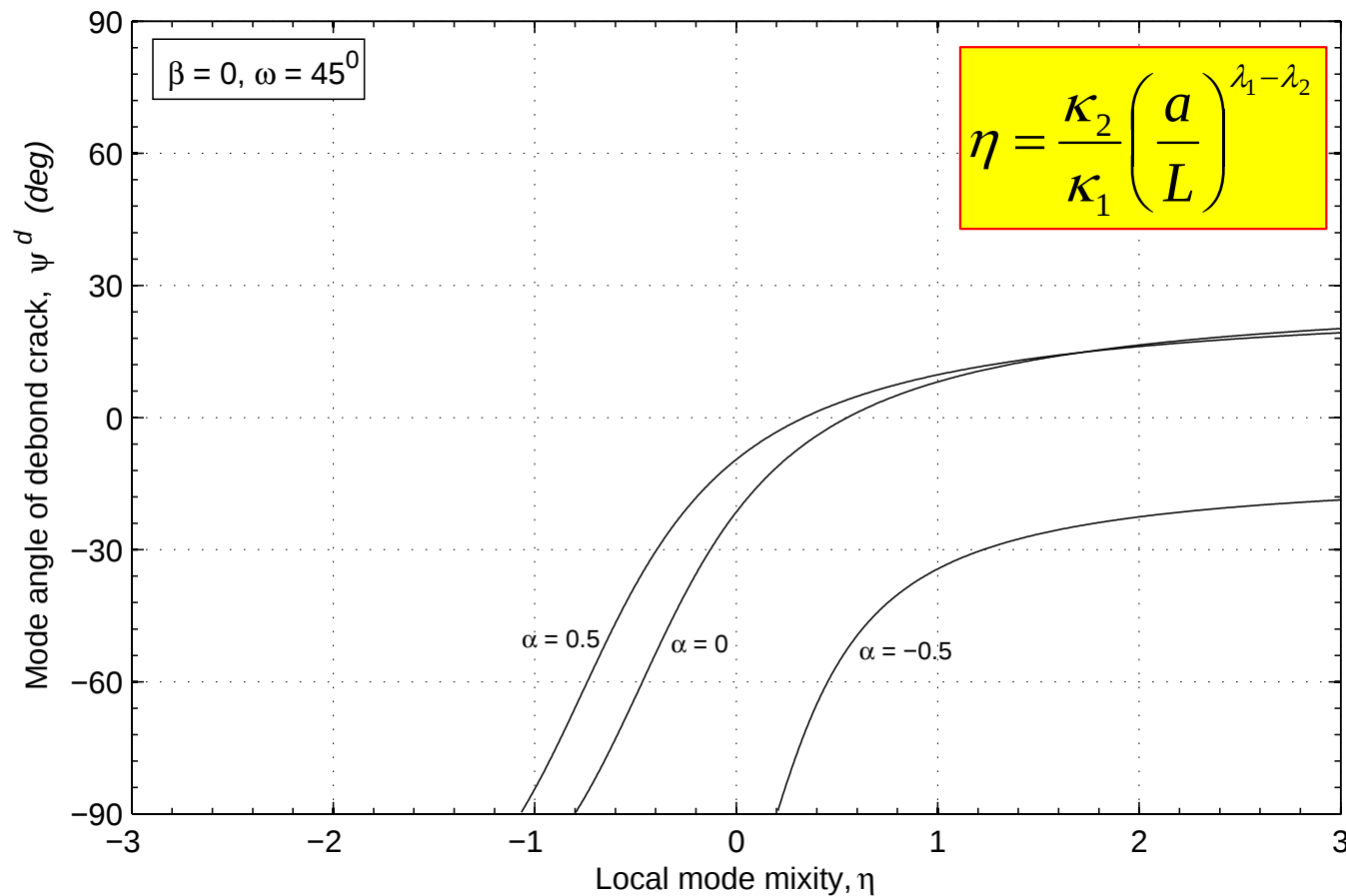
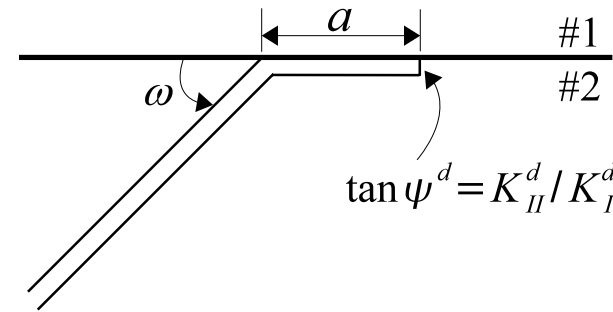
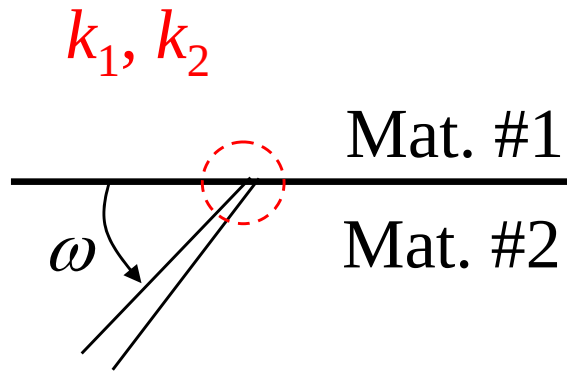


Penetrating angle vs. mode mixity



Weaker singularity plays role via **mode mixity**.

Debonding



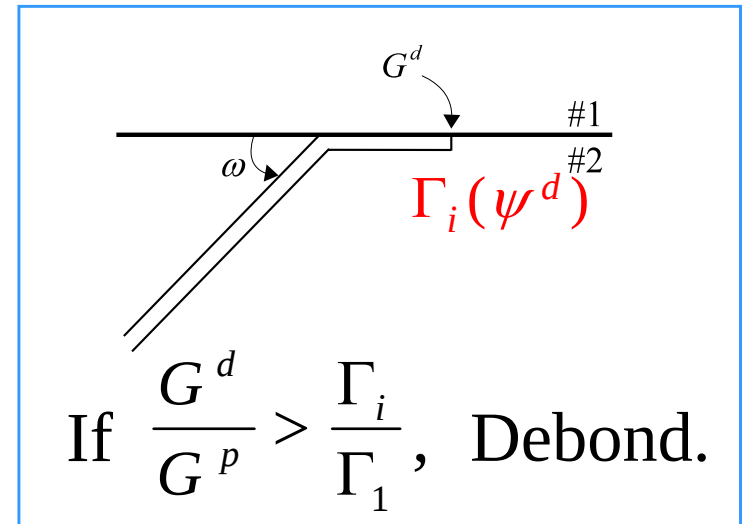
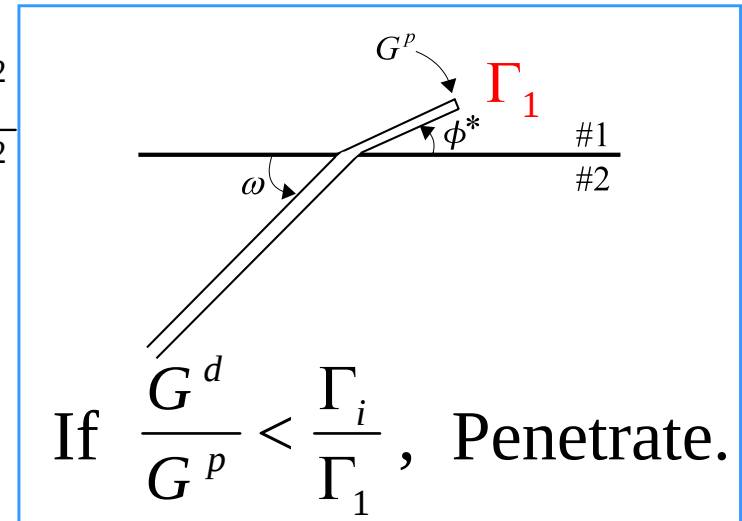
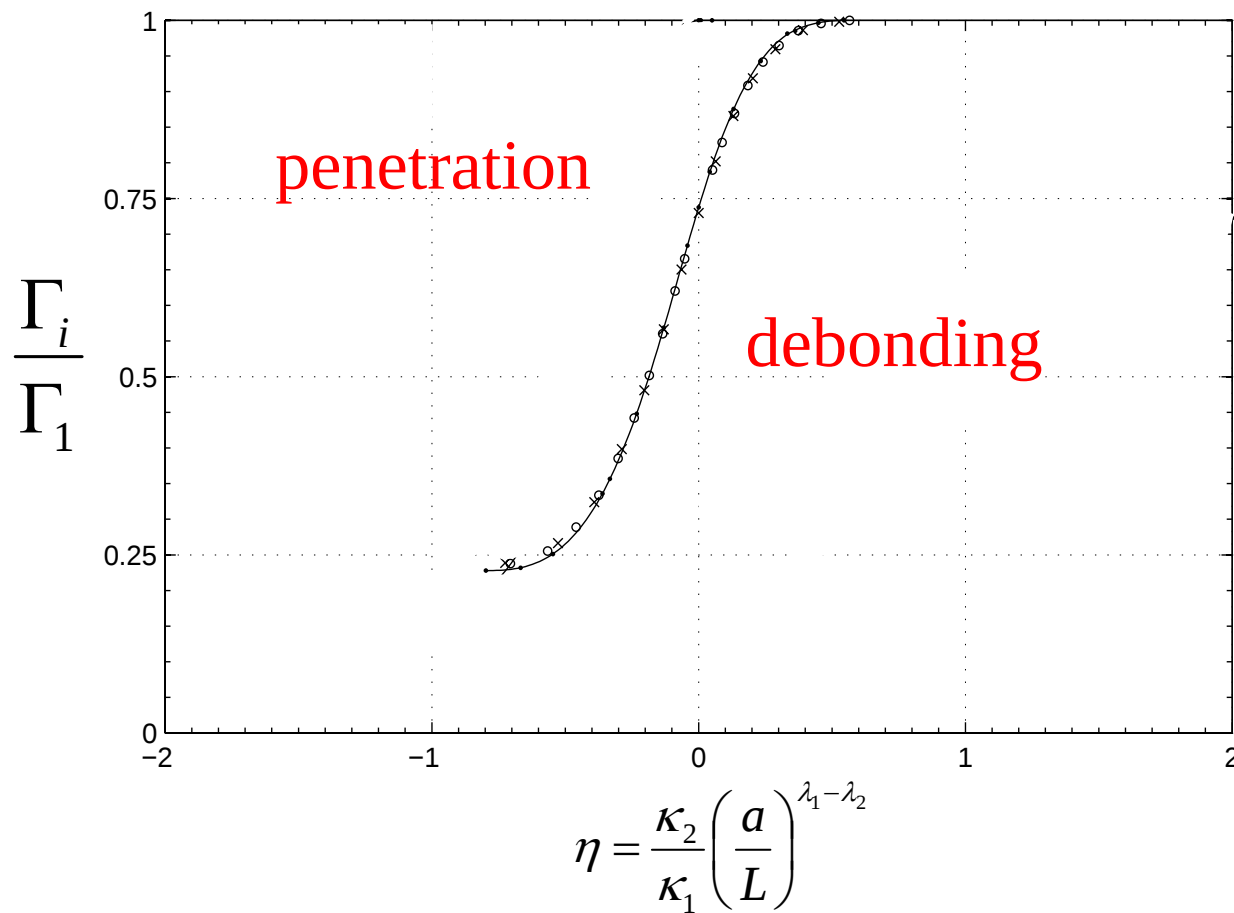
$$\frac{K_I^d}{\sqrt{a}} = c_{11} \cdot \frac{k_1}{a^{\lambda_1}} + c_{12} \cdot \frac{k_2}{a^{\lambda_2}}$$

$$\frac{K_{II}^d}{\sqrt{a}} = c_{21} \cdot \frac{k_1}{a^{\lambda_1}} + c_{22} \cdot \frac{k_2}{a^{\lambda_2}}$$



Penetration vs. Debonding

$$\frac{G^d}{G^p} = \frac{1}{1-\alpha} \cdot \frac{(c_{11}^2 + c_{21}^2) + 2(c_{11}c_{12} + c_{21}c_{22})\eta + (c_{12}^2 + c_{22}^2)\eta^2}{(b_{11}^2 + b_{21}^2) + 2(b_{11}b_{12} + b_{21}b_{22})\eta + (b_{12}^2 + b_{22}^2)\eta^2}$$



Weaker singularity can readily change the outcome of the penetration-debond competition

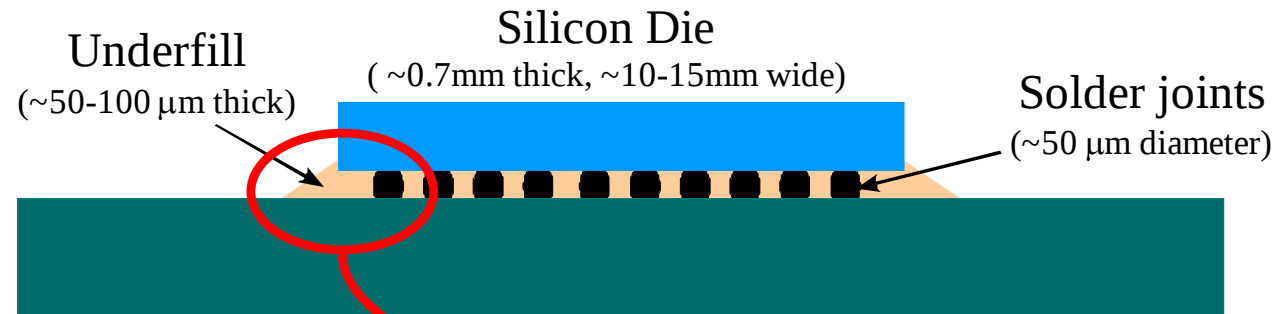


Applications and Implications: #2

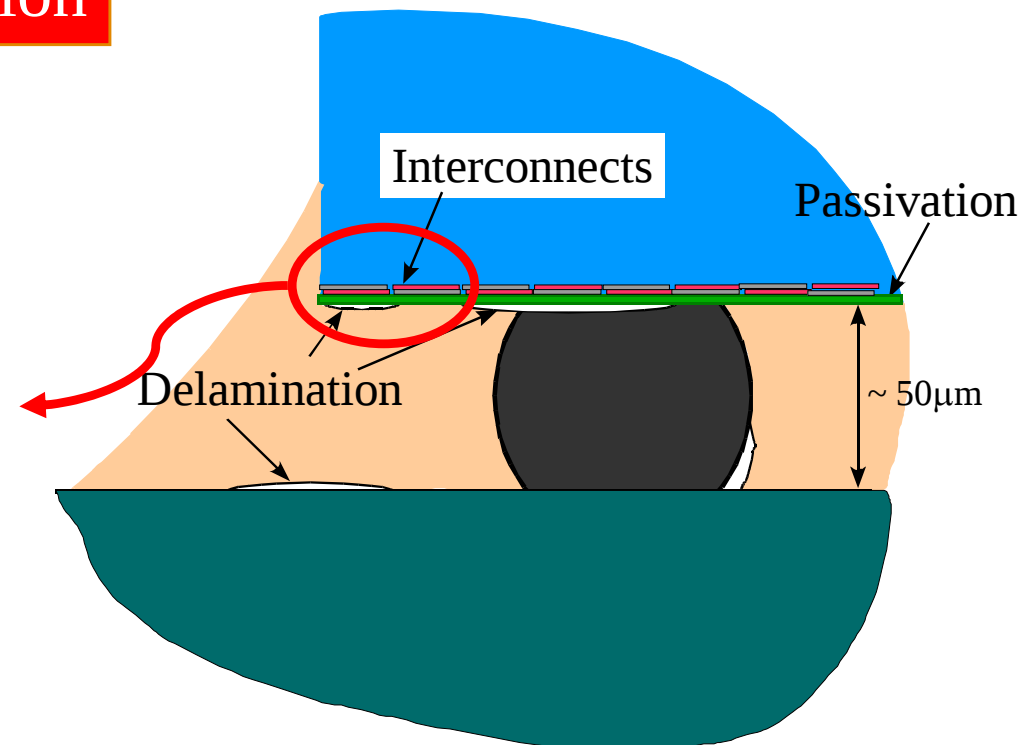
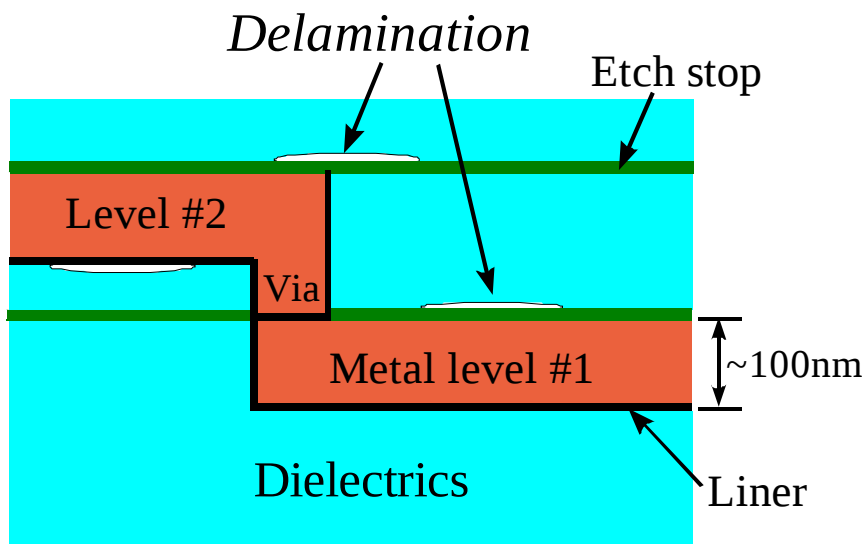
Interfacial Delamination
due to
Chip-Package Interaction



Multi-level structure of flip-chip



Stress concentration





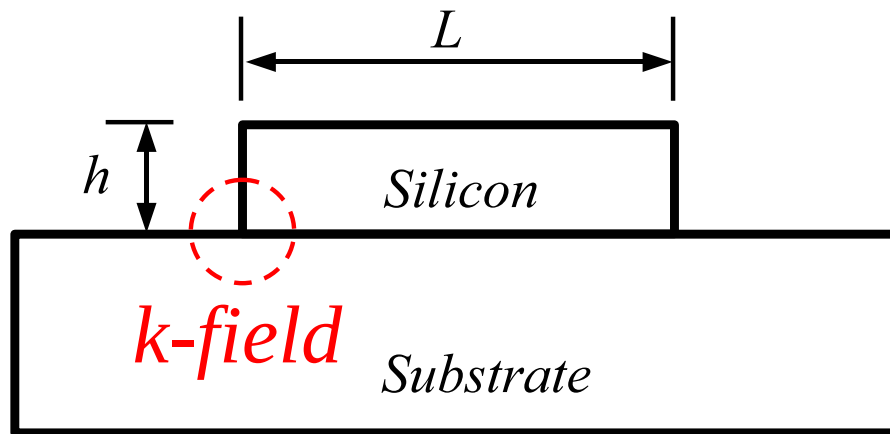
Observations:

- Failure mode: **interfacial delamination**
- Driving force: **chip-packaging interaction**

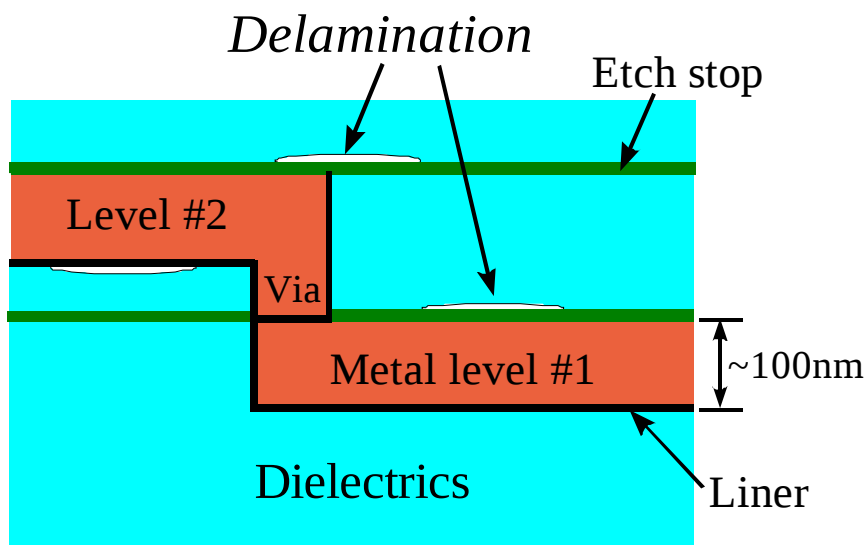
Challenges:

- Huge variation in length scales: **$\sim\text{nm}$ to $\sim\text{cm}$**
- 3D multilevel structures
- Diverse materials interaction
- **Global-local FEM is adopted in industry.**

Simplified model



$$\sigma_{ij}(r, \theta) = \frac{k_1}{r^{\lambda_1}} \Sigma_{ij}^1(\theta) + \frac{k_2}{r^{\lambda_2}} \Sigma_{ij}^2(\theta)$$

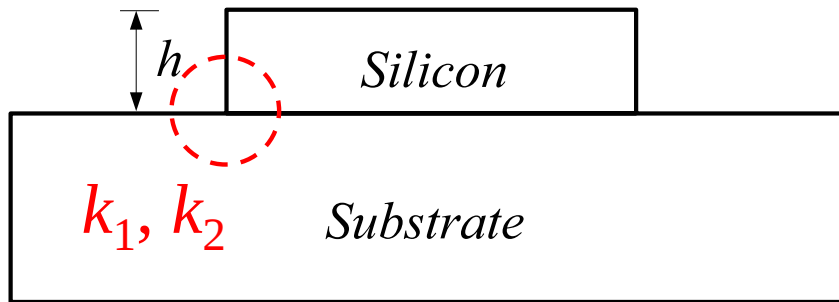


- k -field scales with h .
- Small feature size is within k -field.
- Same macroscopic driving force motivates different flaws to grow.
- The same flaw size and orientation, the same ERR.
- Maybe different toughness.
- Local driving force is much smaller than global driving force.



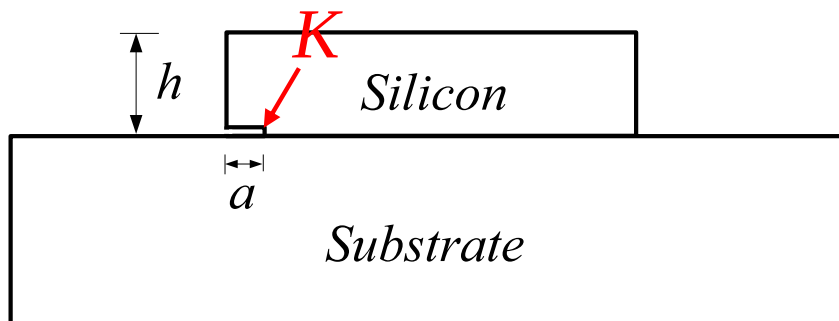
k -field and K -field

Chip-package interaction:



$$\sigma_{ij}(r, \theta) = \frac{k_1}{r^{\lambda_1}} \Sigma_{ij}^1(\theta) + \frac{k_2}{r^{\lambda_2}} \Sigma_{ij}^2(\theta)$$

Interfacial delamination:



$$\frac{\text{Re}(Ka^{i\varepsilon})}{\sqrt{a}} = c_{11} \cdot \frac{k_1}{a^{\lambda_1}} + c_{12} \cdot \frac{k_2}{a^{\lambda_2}}$$

$$\frac{\text{Im}(Ka^{i\varepsilon})}{\sqrt{a}} = c_{21} \cdot \frac{k_1}{a^{\lambda_1}} + c_{22} \cdot \frac{k_2}{a^{\lambda_2}}$$

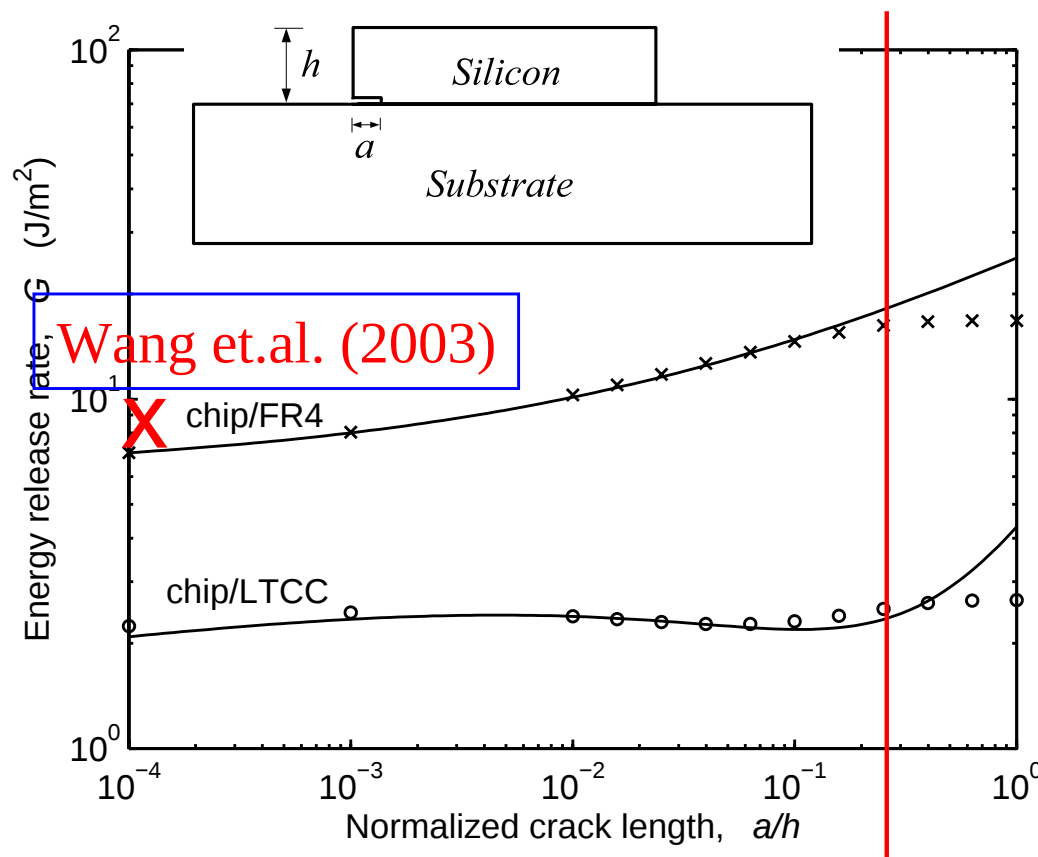


Length dependence of mode mixity

$$G = \frac{1-\beta^2}{1-\alpha} \frac{\kappa_1^2 \sigma^2 h}{\bar{E}_{Si}} \left(\frac{a}{h} \right)^{1-2\lambda_1} \left[(c_{11} + c_{12}\eta)^2 + (c_{21} + c_{22}\eta)^2 \right]$$

$$\eta = \frac{\kappa_2}{\kappa_1} \left(\frac{a}{h} \right)^{\lambda_1 - \lambda_2}$$

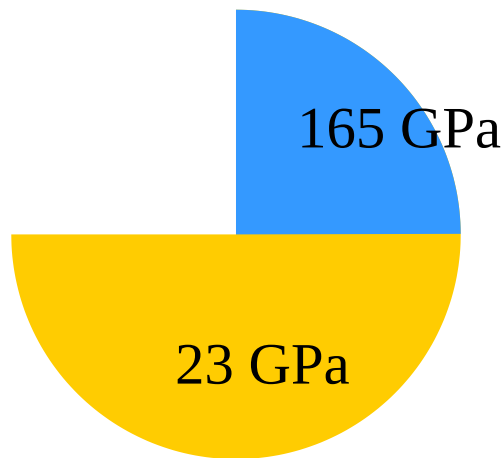
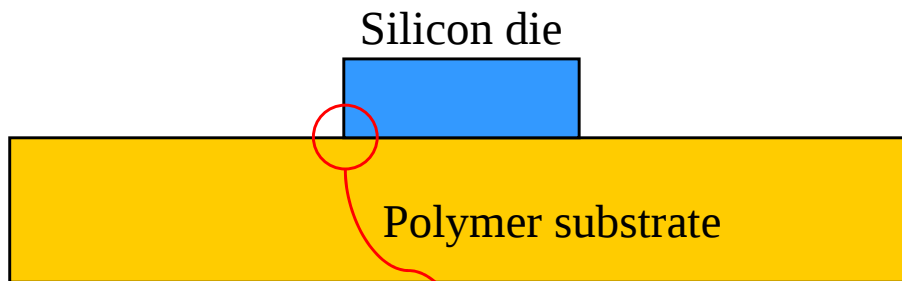
Thermal excursion $\Delta T = 140^\circ\text{C}$



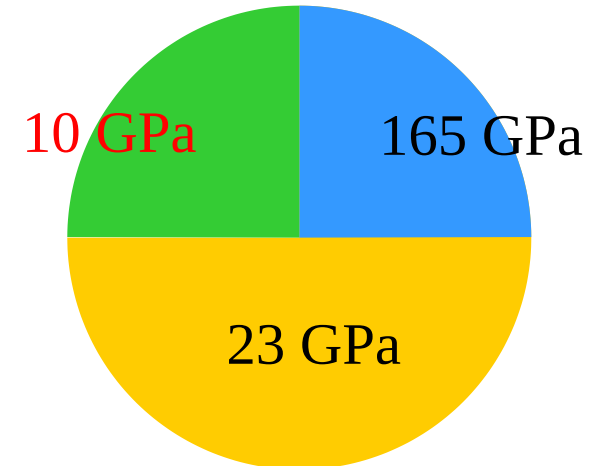
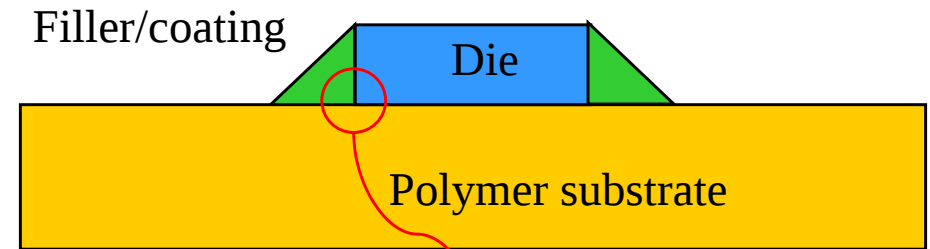
- Similar value as multi-scale calculation.
- k -field applies if $a/h < 1/4$.
- Break-down of power law of $G \sim a$ relation.
- G hardly goes to zero.



Reduction in singularity



$$\lambda_1 = 0.497 \quad \lambda_2 = 0.346$$



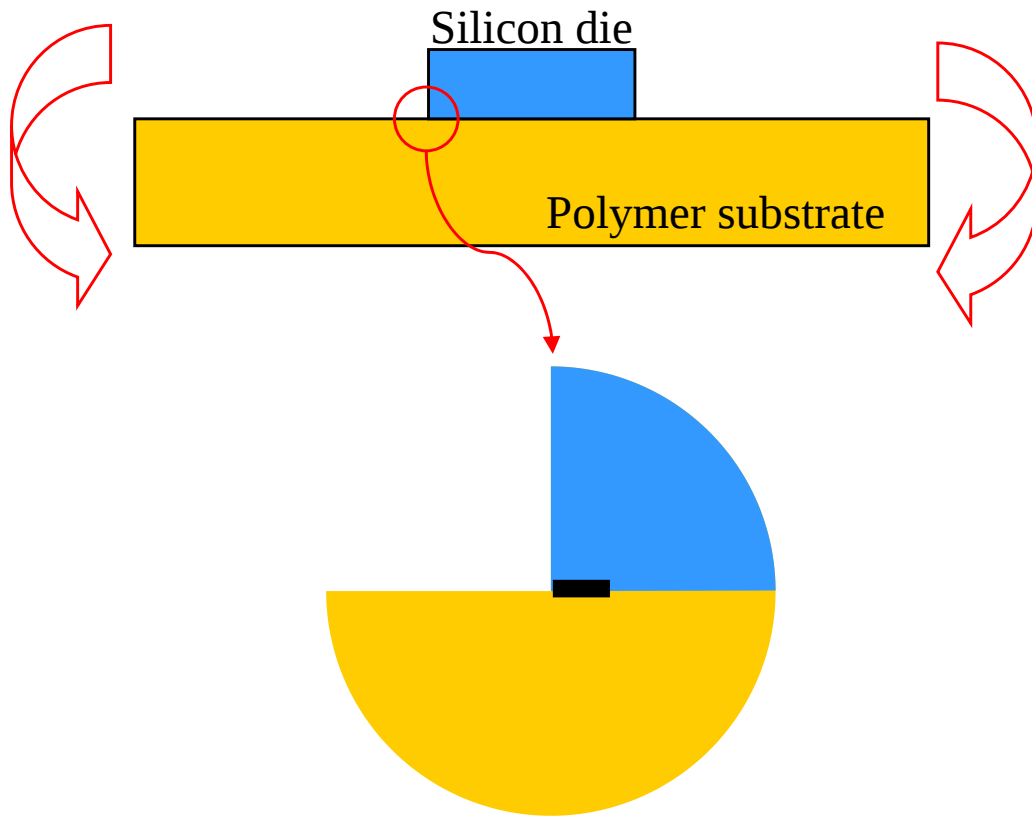
$$\lambda_1 = 0.3 \quad \lambda_2 = 0.247$$

Singularities are reduced a lot by using a filler or coating. *Why?*

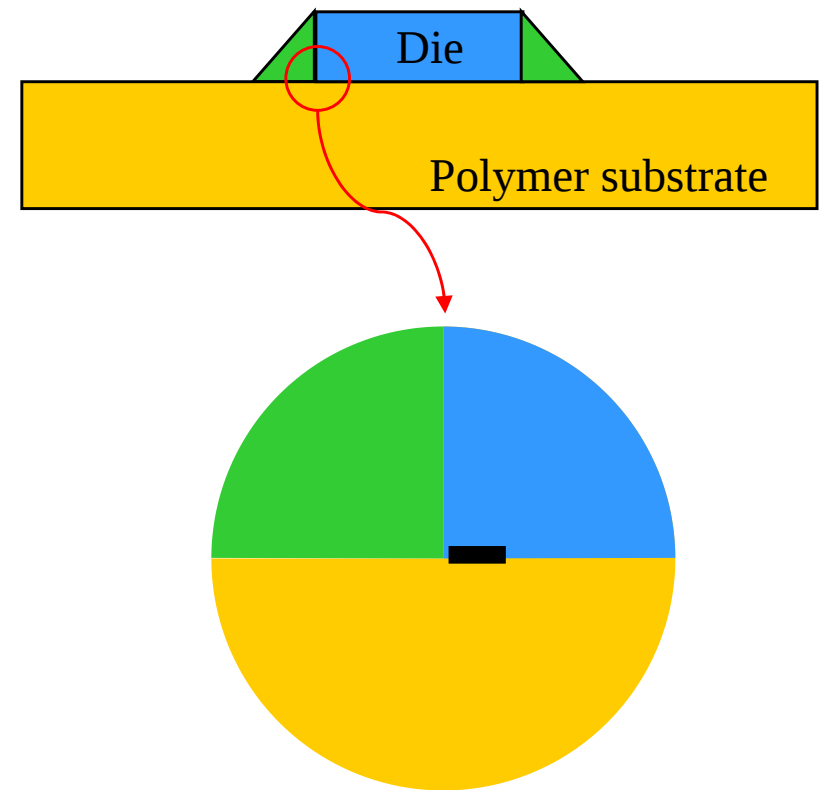
Elastic mismatch is reduced and geometric discontinuity is closed.



Suppression of debonding



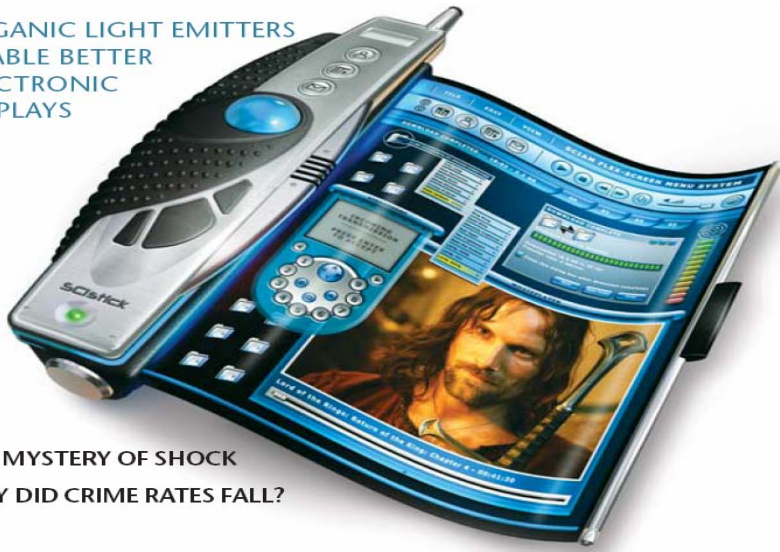
Free surfaces are easy to deform,
interfacial flaw is easy to open.



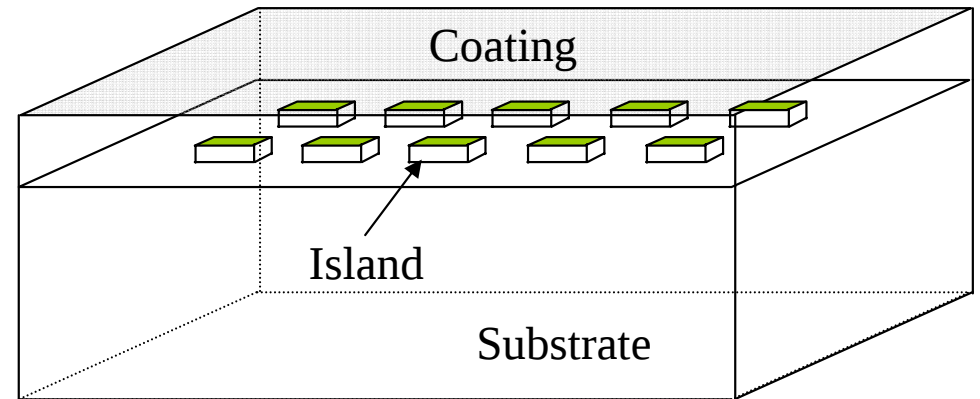
The opening of the debonded
interface is suppressed.

Example in flexible electronics

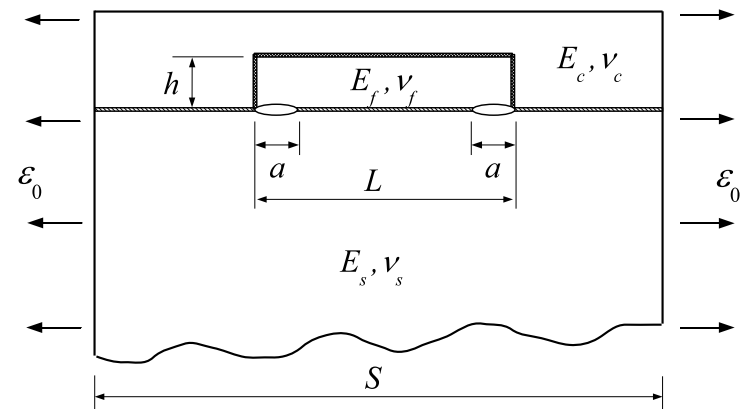
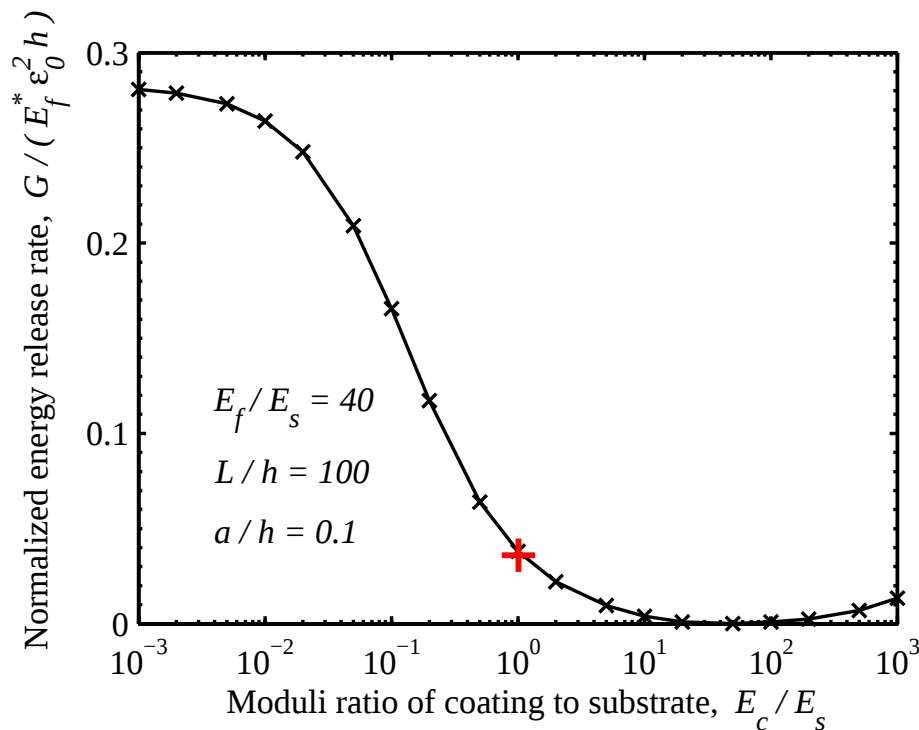
ORGANIC LIGHT EMITTERS
ENABLE BETTER
ELECTRONIC
DISPLAYS



THE MYSTERY OF SHOCK
WHY DID CRIME RATES FALL?



- Enhance the **survival rate**
- Increase the **island size**



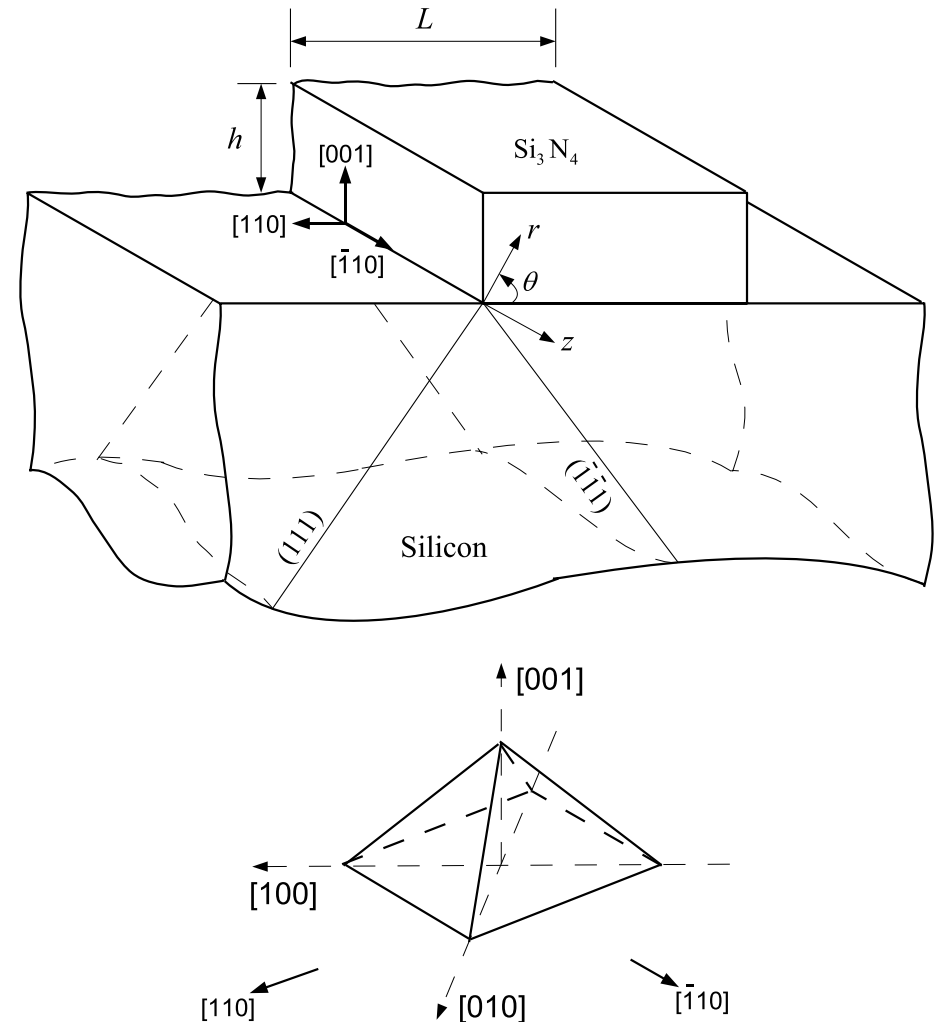


Applications and Implications: #3

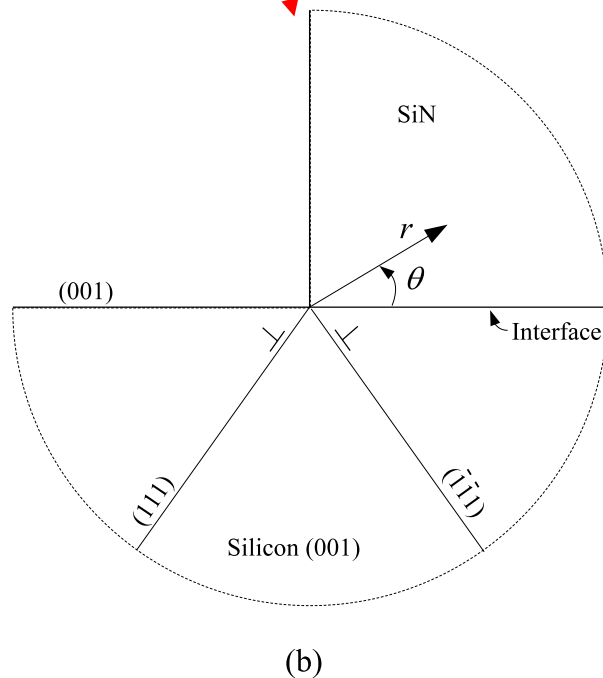
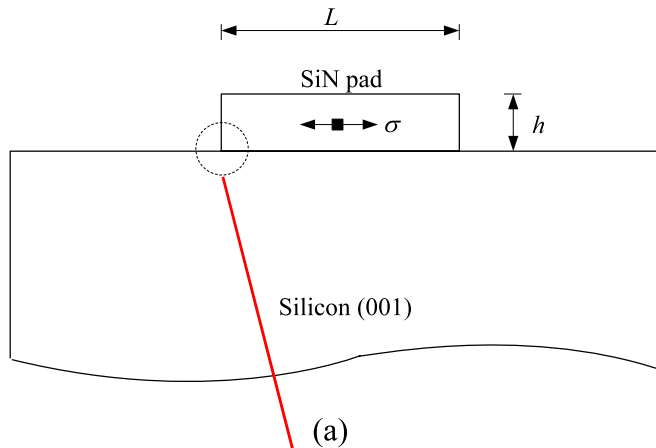
Dislocation Injection
From Sharp Features
In Strained Silicon Structures

Strained silicon structure

- **Stresses** are deliberately introduced to increase carrier mobility.
- **Edges** and **corners** intensify stresses, inject dislocations and **fail** the device.
- Objective: **critical conditions** that avert dislocations, on the basis of singular stress fields near the sharp features.



Simplification



$$\sigma_{ij}(r, \theta) = \frac{k_1}{r^{\lambda_1}} \Sigma_{ij}^1(\theta) + \frac{k_2}{r^{\lambda_2}} \Sigma_{ij}^2(\theta)$$

$$\lambda_1 = 0.4514 \quad \lambda_2 = 0.0752$$

$$\eta = \frac{\kappa_2}{\kappa_1} \left(\frac{b}{h} \right)^{\lambda_1 - \lambda_2}$$

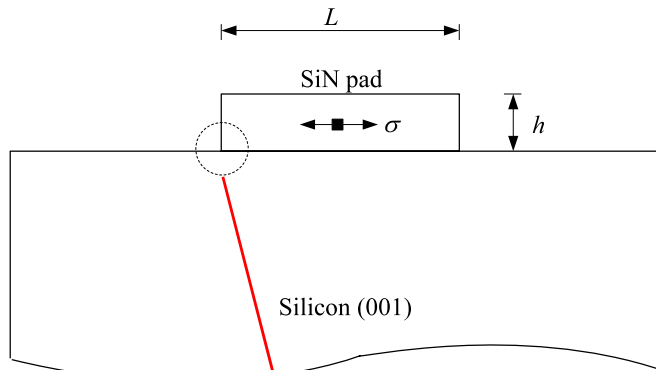
$$b = 0.383 \text{ nm}$$

$$h = 100 \text{ nm}$$

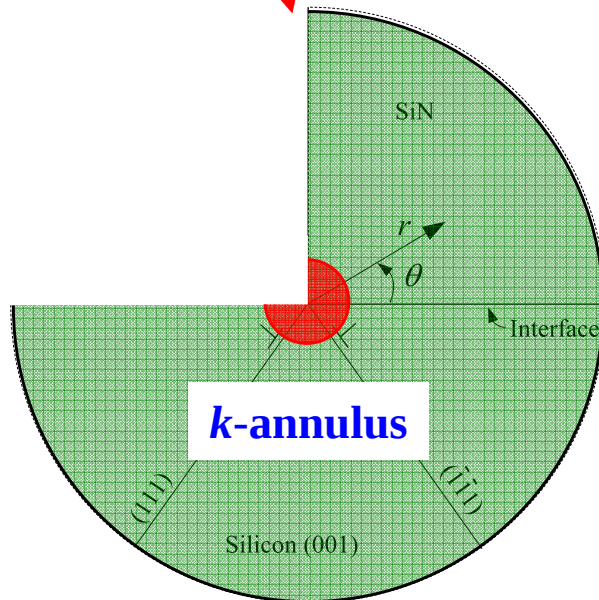
$$\eta \sim 0.02$$

$$\sigma_{ij}(r, \theta) = \frac{k}{r^\lambda} \Sigma_{ij}(\theta)$$

Stress intensity factor k



(a)



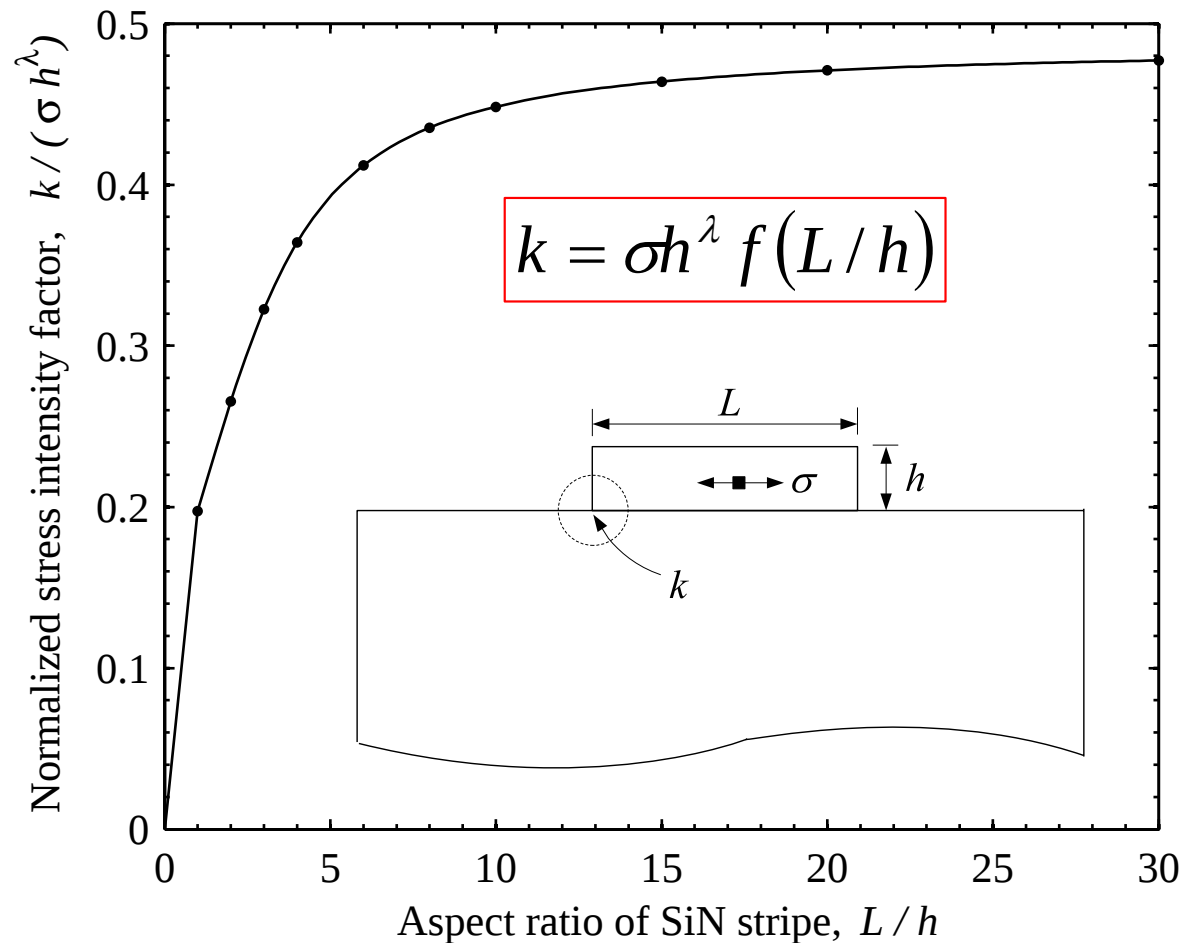
(b)

$$k = \sigma h^{\frac{1}{2}} f(L/h)$$

- The driving force of dislocation injection is stress field in k -annulus, which is characterized by k .



Critical stress intensity factor k_c



Critical condition:

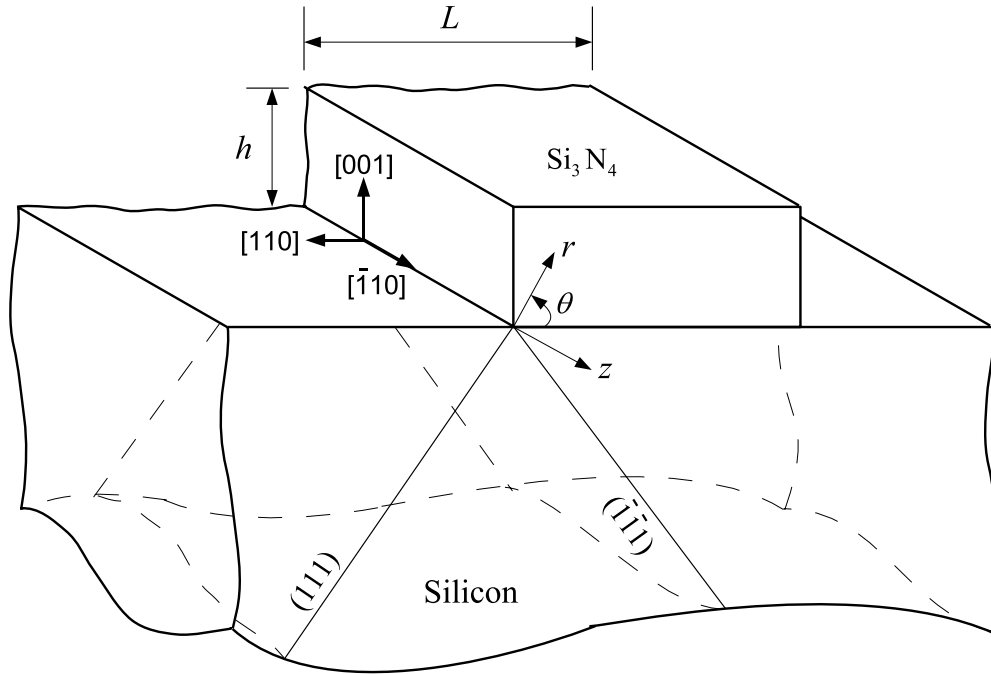
$$k = k_c$$

Driving force

Resistance

k_c is specific to the materials and wedge angle, like fracture toughness.

An estimate of k_c



$$\sigma_{ij}(r, \theta) = \frac{k}{r^\lambda} \Sigma_{ij}(\theta)$$

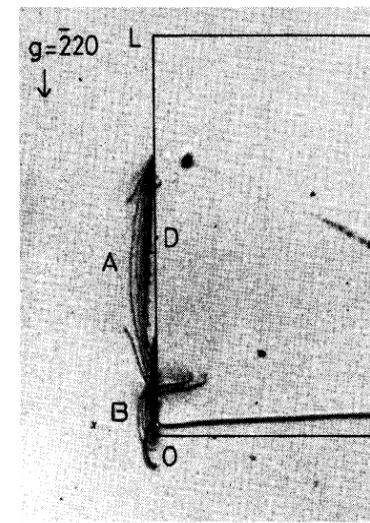
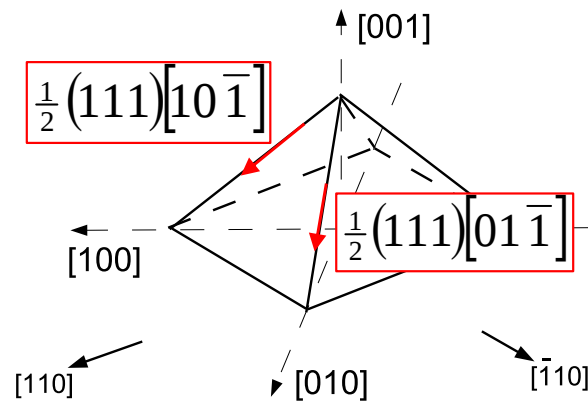
$$\tau_{nb} = \sigma_{ij} n_i b_j$$

$$\tau_{th} = \frac{\mu b}{2\pi d} \cong 0.2\mu$$

Criterion:

$$\tau_{nb} \big|_{r=b} = \tau_{th}$$

$$k_c = 0.5\mu b^\lambda$$



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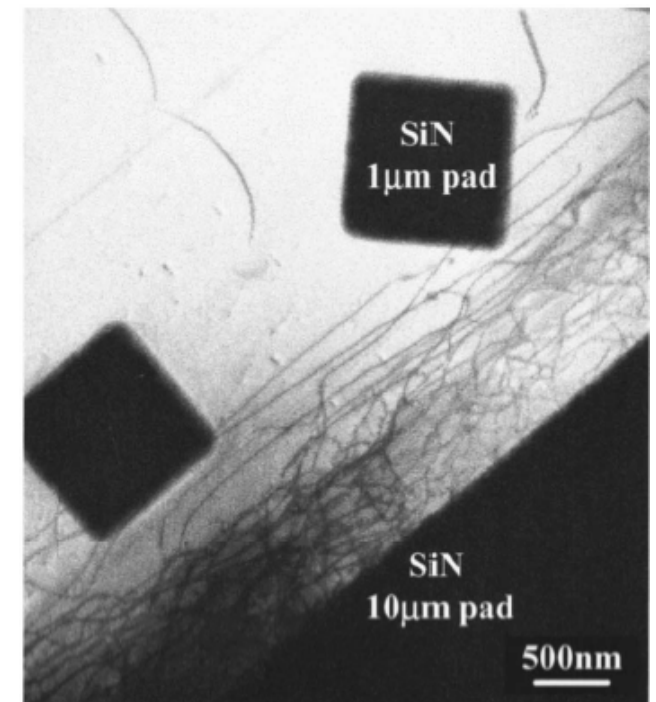
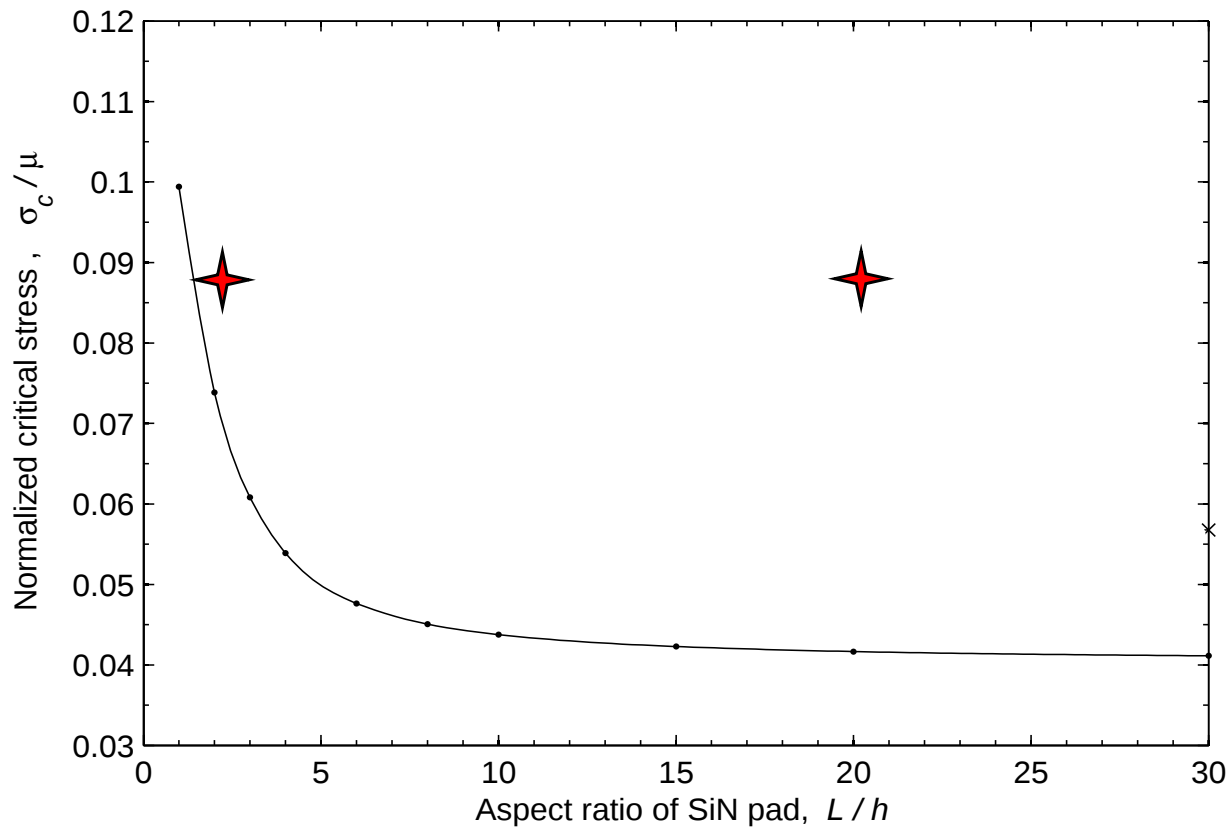
Isomae (1981)

der to ob-
served from
it. Burgers
ectively.

Critical stress in SiN stripe

$$\sigma_c = \frac{0.5\mu}{f(L/h)} \left(\frac{b}{h} \right)^\lambda$$

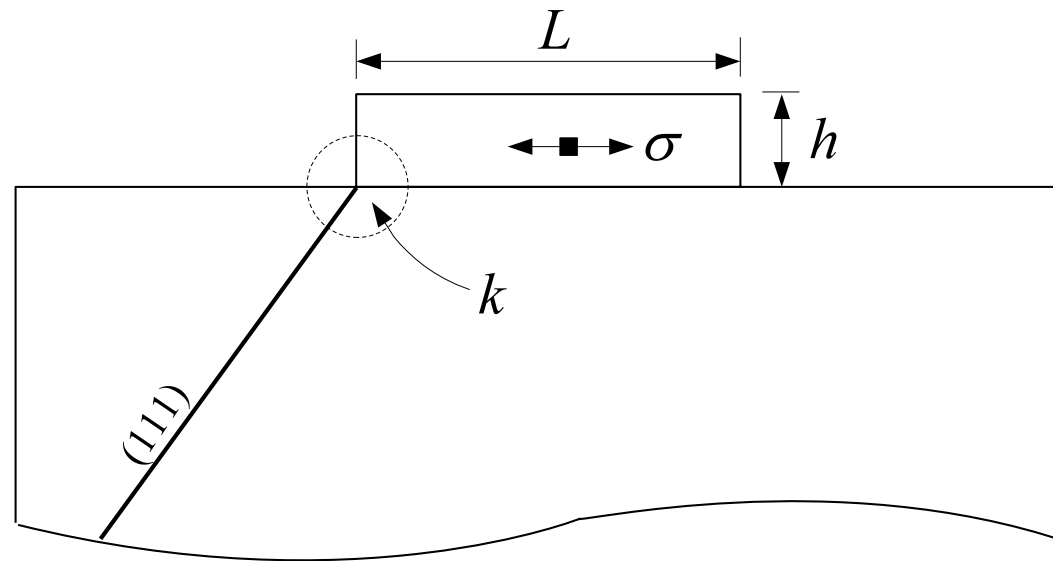
The *wider* and *thicker*,
The *easier* to inject dislocation.



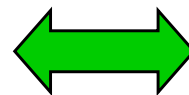
Kammler et al (2005)



Measurement of k_c



Measure k_c :



Calculate k :

$$k = \sigma h^\lambda f(L/h)$$



Summary

- Split singularities:

$$\sigma_{ij}(r, \theta) = \frac{k_1}{r^{\lambda_1}} \Sigma_{ij}^1(\theta) + \frac{k_2}{r^{\lambda_2}} \Sigma_{ij}^2(\theta)$$

- Mode mixity depends on two lengths:

$$\eta = \left(\frac{\kappa_2}{\kappa_1} \right) \left(\frac{\Lambda}{L} \right)^{\lambda_1 - \lambda_2}$$



Acknowledgements

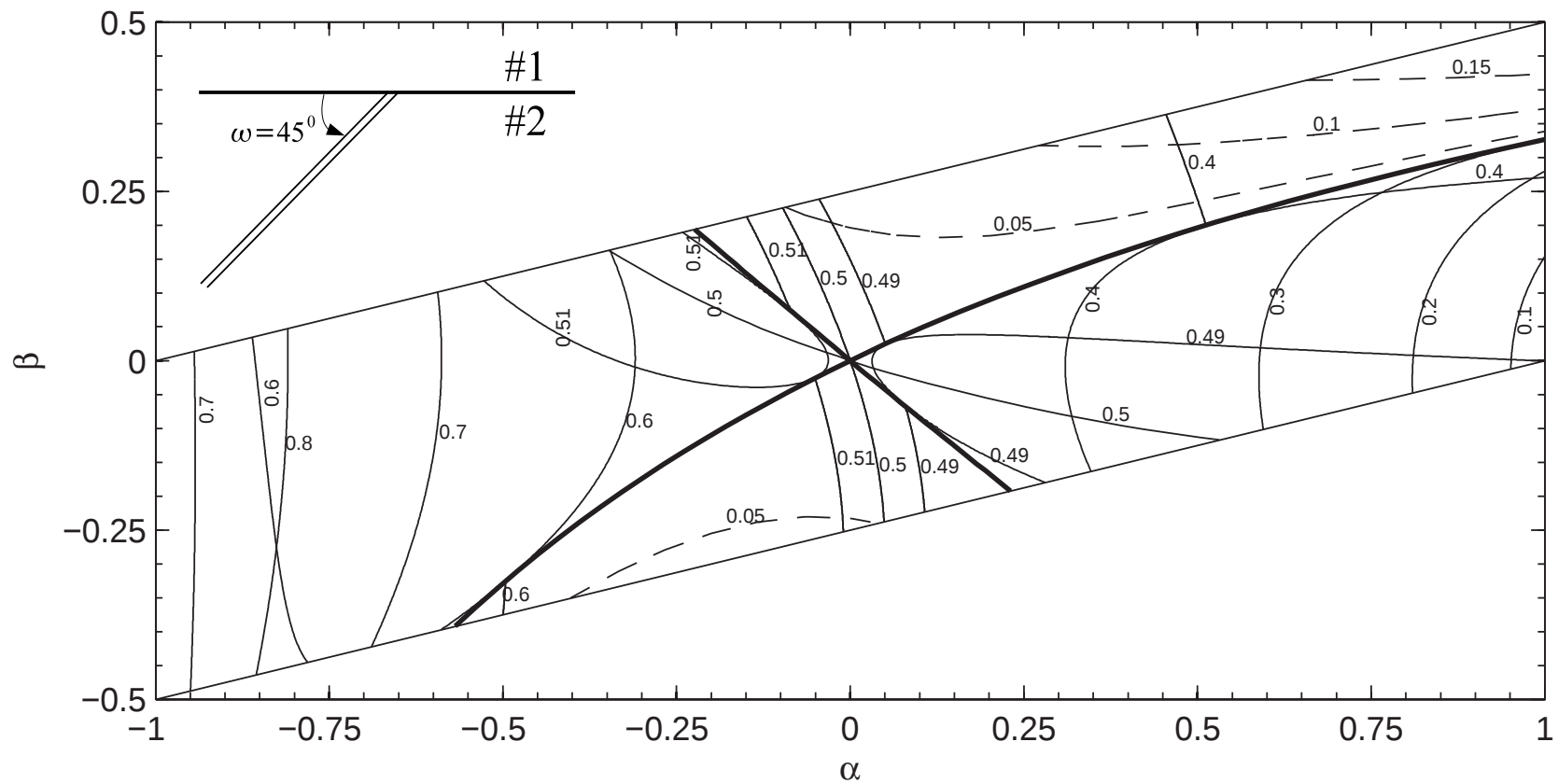
- Advisor: Zhigang Suo
- Committee: John Hutchinson
Joost Vlassak
Frans Spaepen
- Collaborators: Juil Yoon, Nanshu Lu, Martijn Feron, Jun He, Jim Liang, Jean Prevost, etc.
- Group members: Wei Hong, Xuanhe Zhao, Jinxiong Zhou, Dunming Liao, etc.

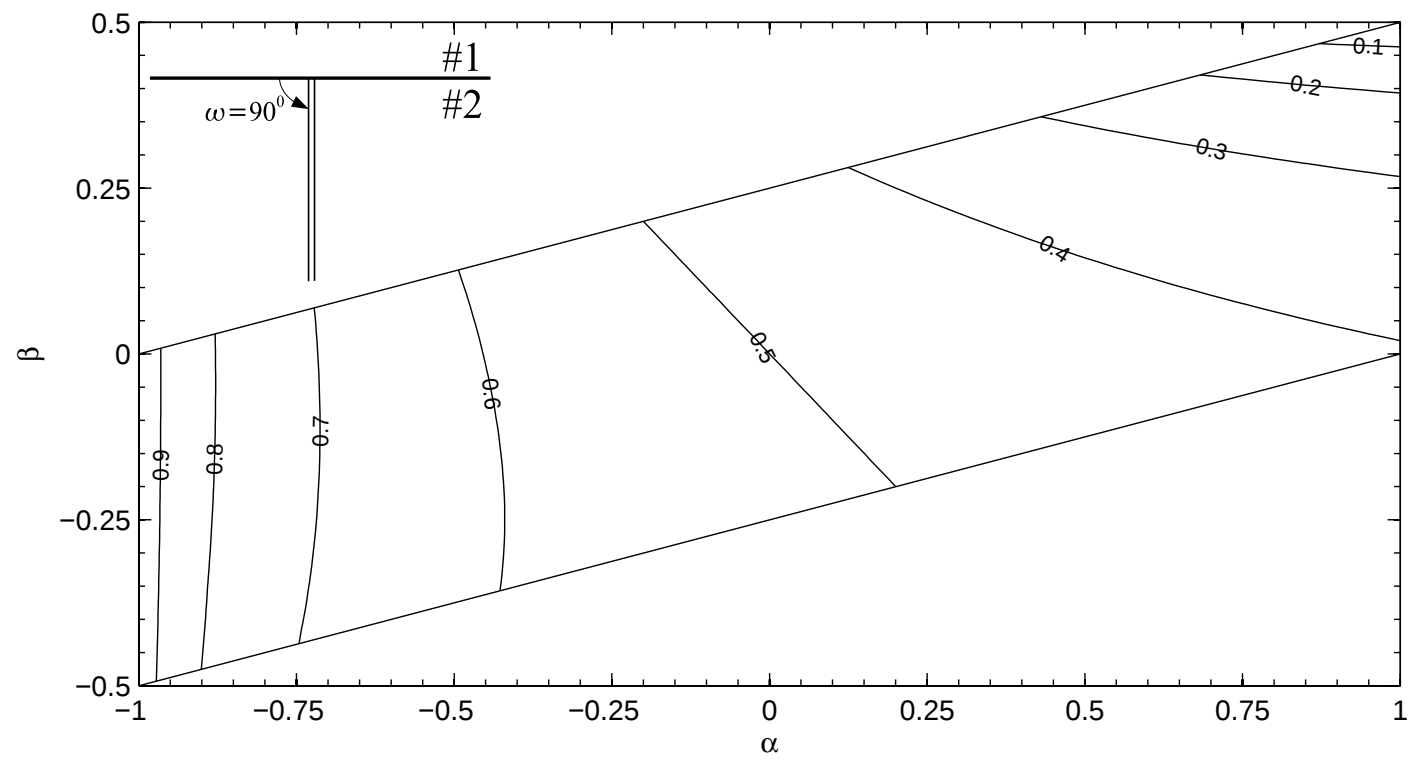


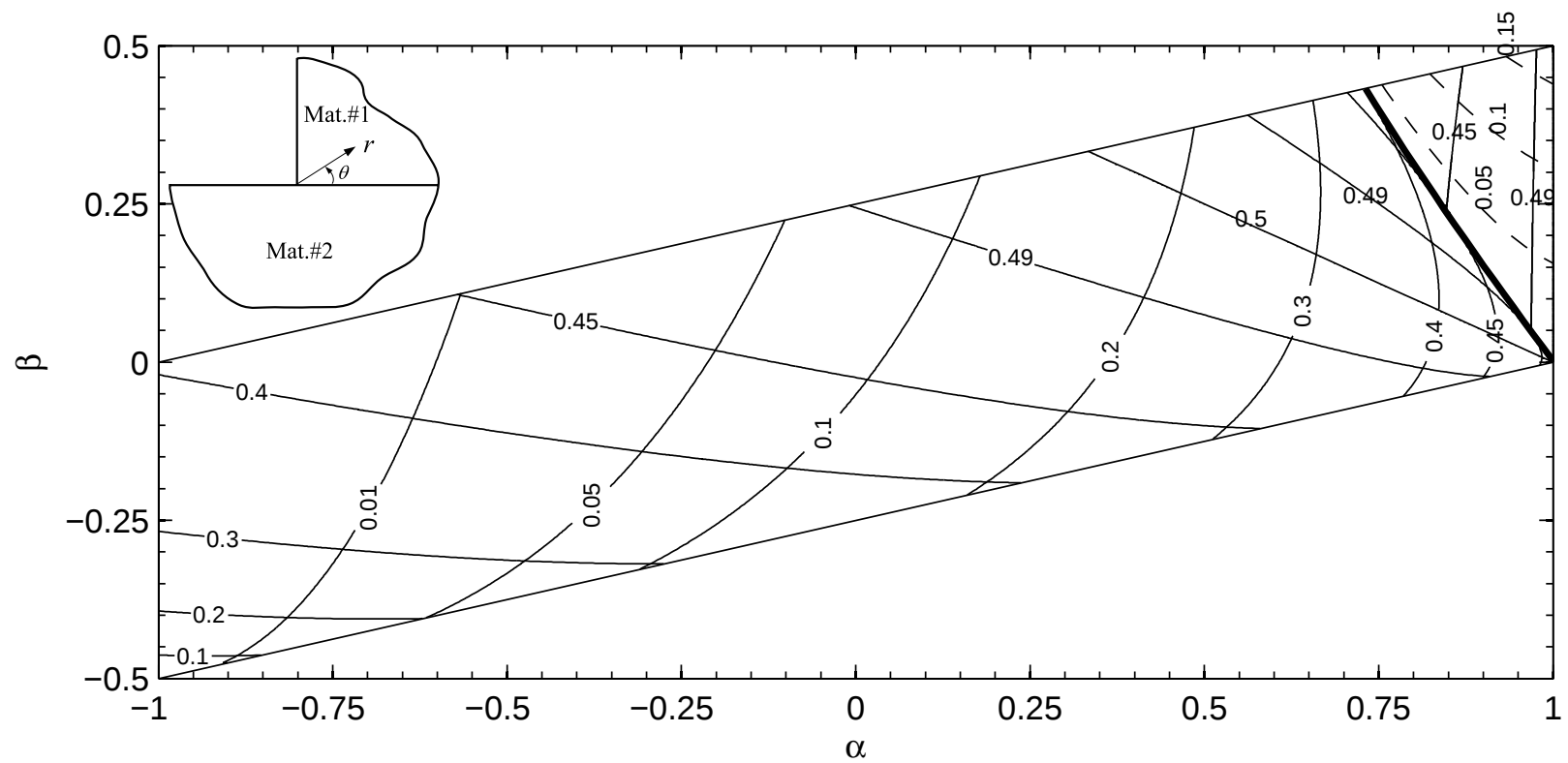
Backup slides for split singularities

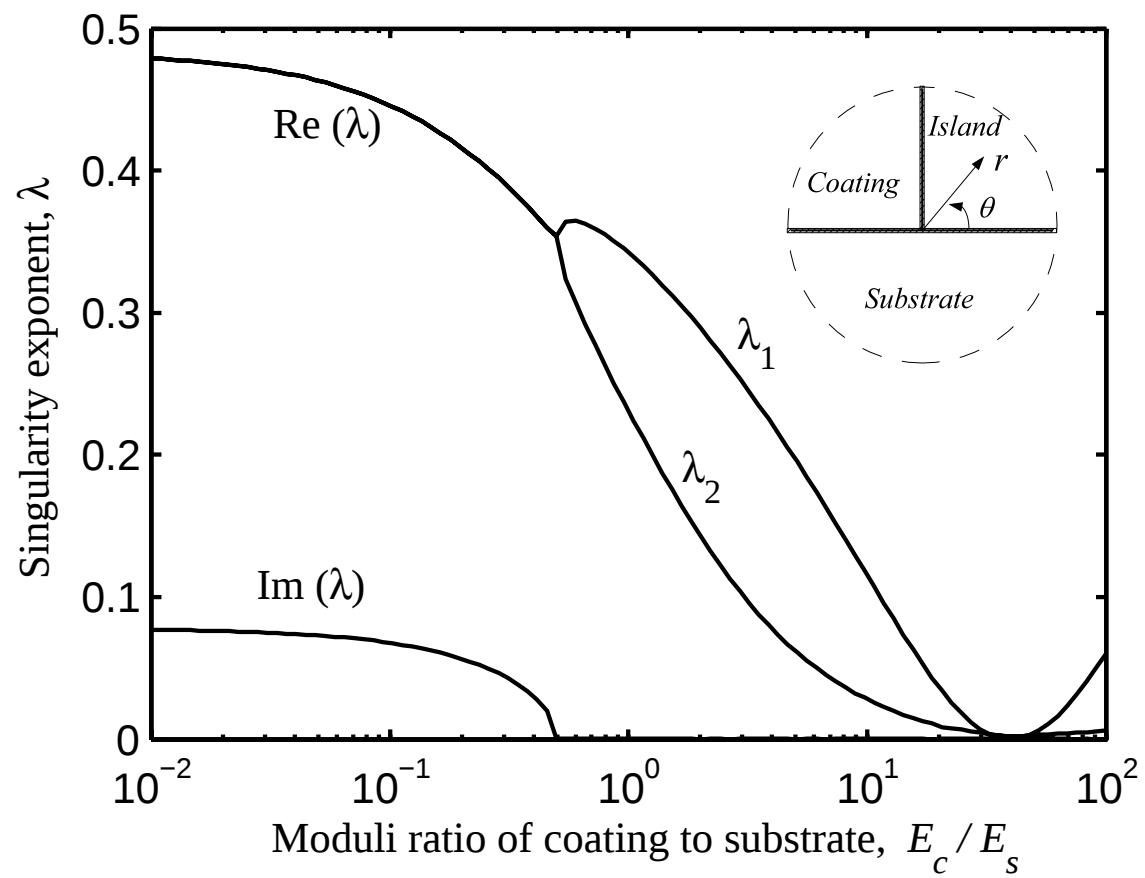


Split singularities

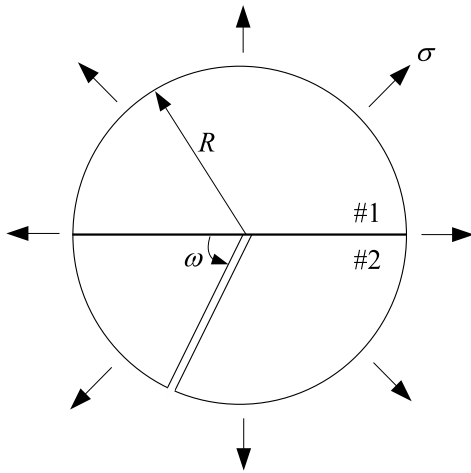




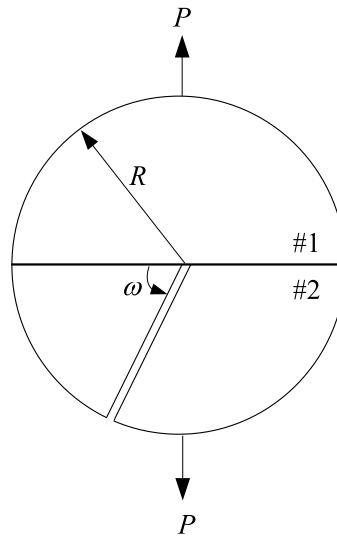




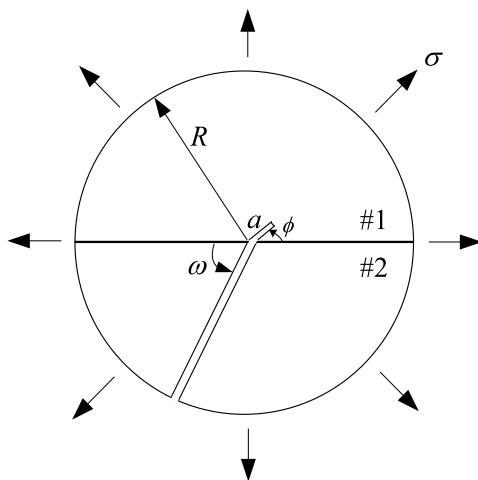
(a)



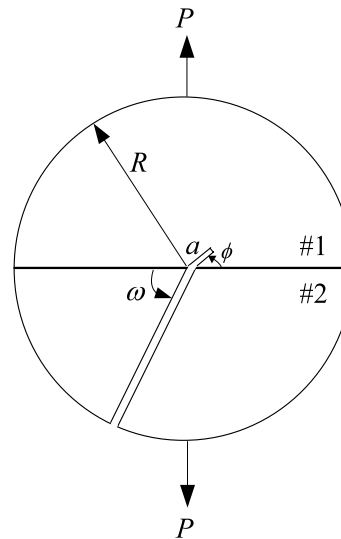
(b)



(a)



(b)



$$\frac{K_I^P}{\sqrt{a}} = b_{11} \cdot \frac{k_1}{a^{\lambda_1}} + b_{12} \cdot \frac{k_2}{a^{\lambda_2}}$$

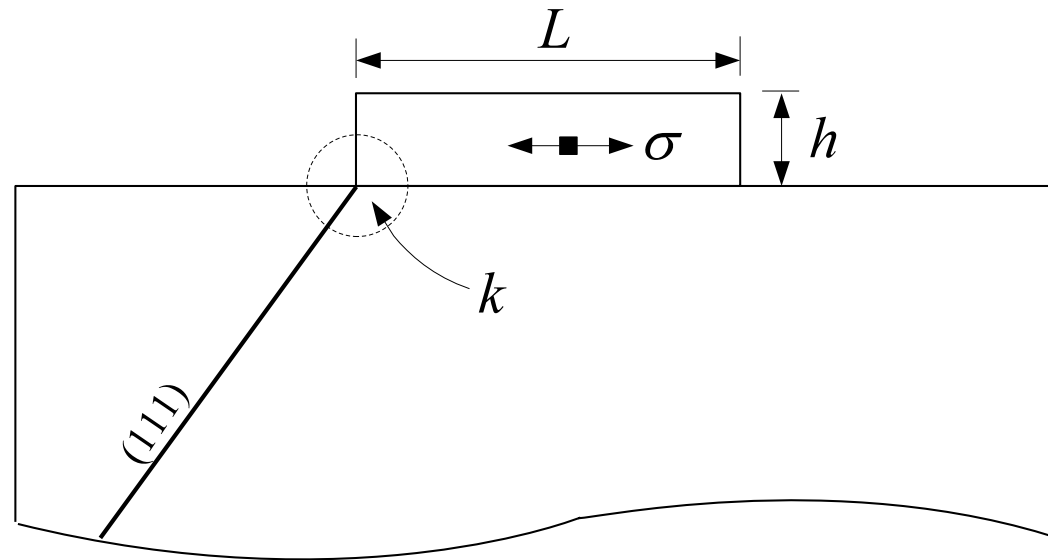
$$\frac{K_{II}^P}{\sqrt{a}} = b_{21} \cdot \frac{k_1}{a^{\lambda_1}} + b_{22} \cdot \frac{k_2}{a^{\lambda_2}}$$



Backup slide for strained silicon

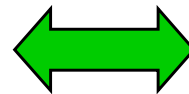


Measurement of k_c



Dimensional requirement:

$$k_c = c \cdot \mu b^\lambda$$



A series of experiments:

$$k = \sigma h^\lambda f(L/h)$$

Find a critical condition to obtain coefficient c by:

$$c = \frac{\sigma}{\mu} \cdot \left(\frac{h}{b}\right)^\lambda \cdot f\left(\frac{L}{h}\right)$$

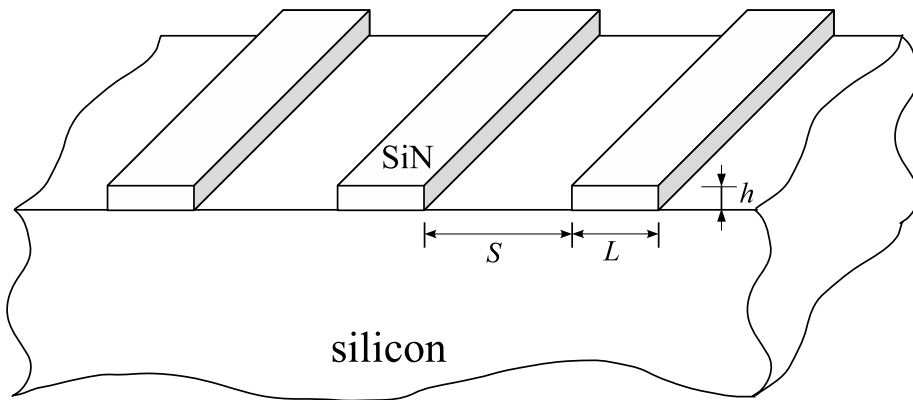


Other concerns from industry

- Periodic patterned, so how is the spacing effect?
- 3D corner is more singular than 2D wedge. Does the current method apply?
- What if I don't use SiN? I chose other materials as stressors.



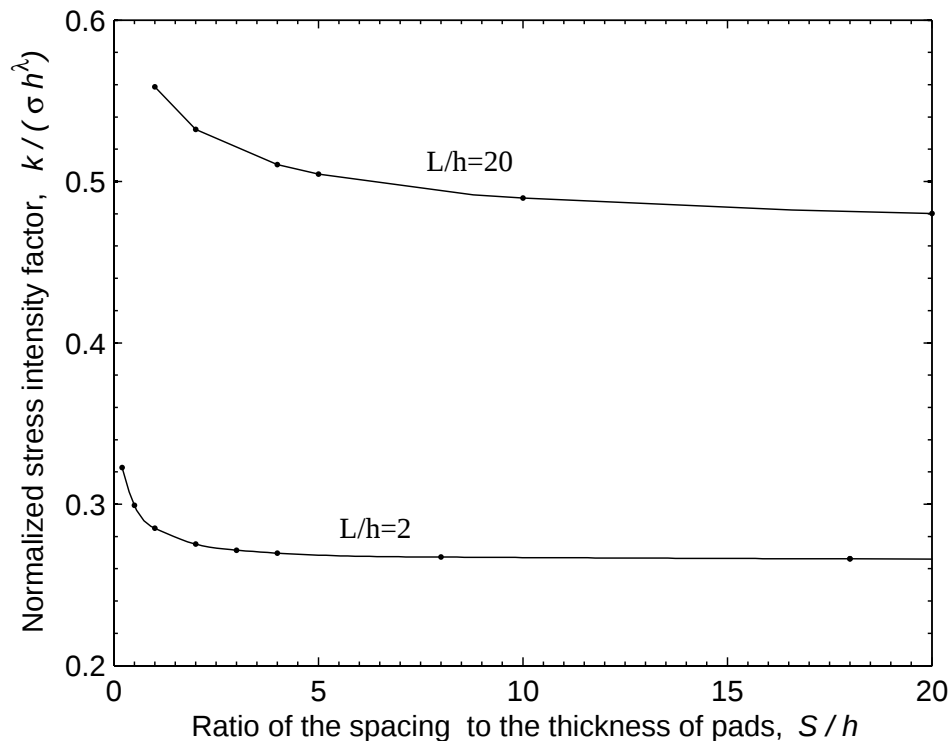
Spacing effect



$$\sigma_{ij}(r, \theta) = \frac{k}{r^\lambda} \Sigma_{ij}(\theta)$$

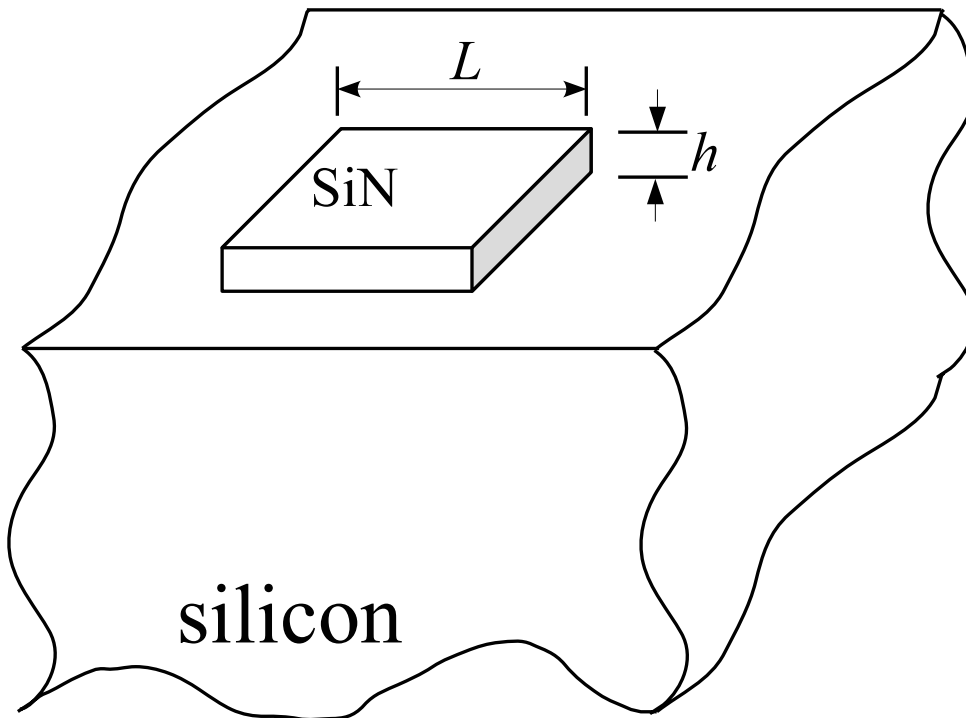
with $\lambda = 0.4514$

$$k = \sigma h^\lambda \cdot f\left(\frac{L}{h}, \frac{S}{h}\right)$$



In practice, S/h doesn't go to zero, so the spacing effect is quite small.

3D Corners

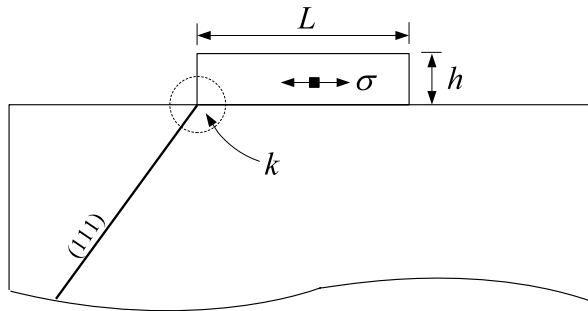


$$k = \sigma h^\lambda \cdot f\left(\frac{L}{h}, \frac{S}{h}, \frac{R}{h}\right)$$

- The method still applies. What changes is the **coefficients**.
- 3D corner singularities. **Measurement of k_c and calculation of $f(L/h, S/h, R/h)$.**
- 3D calculation is expensive for academia, but very cheap for industry. *Do it.*

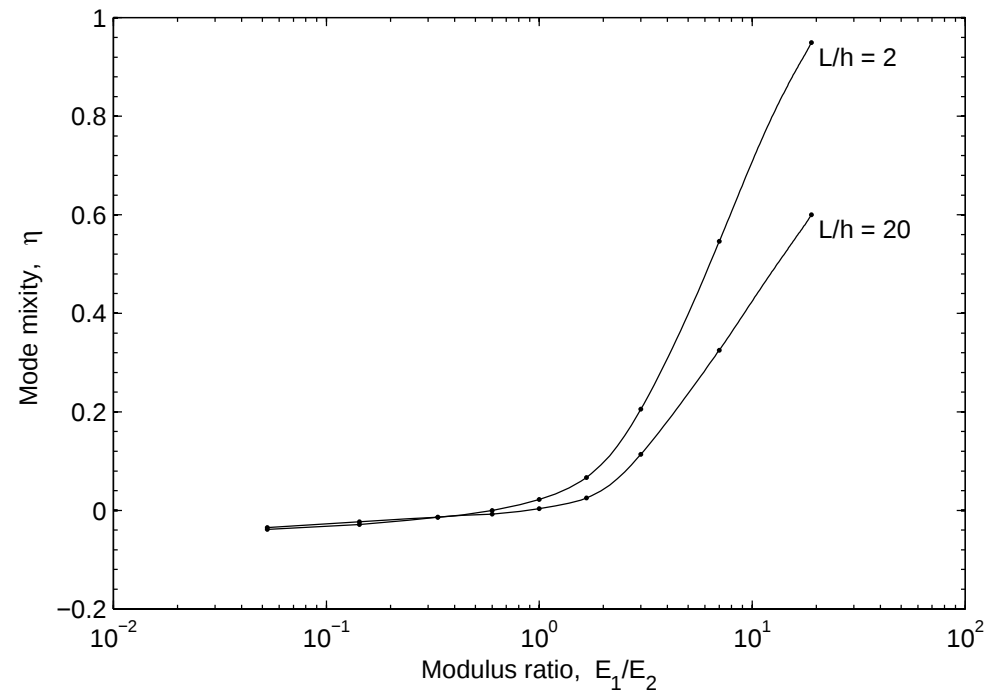
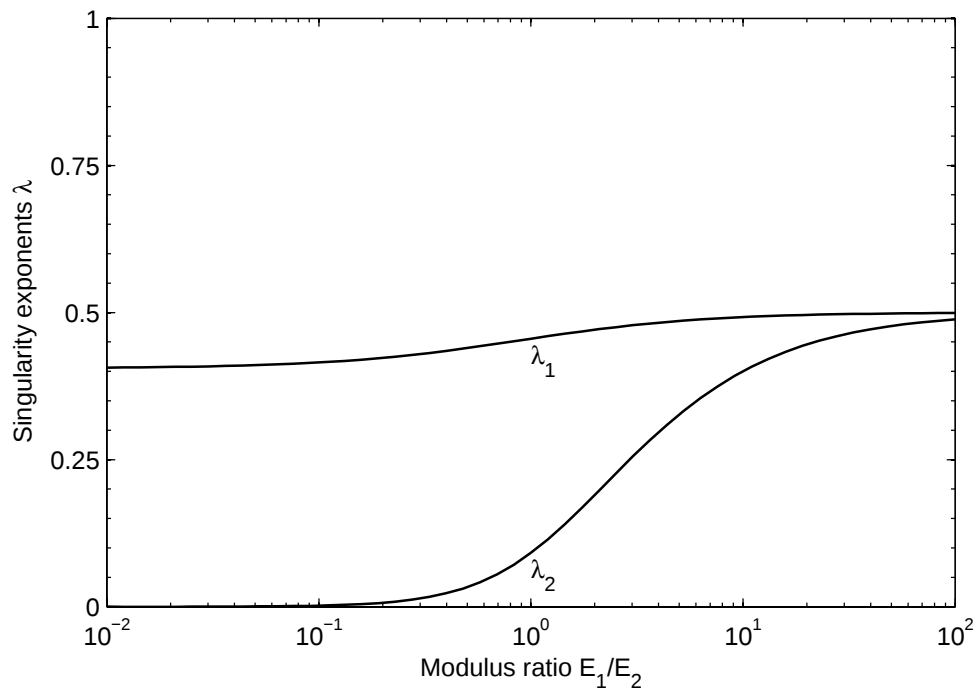


Effect of weaker singularity if not SiN



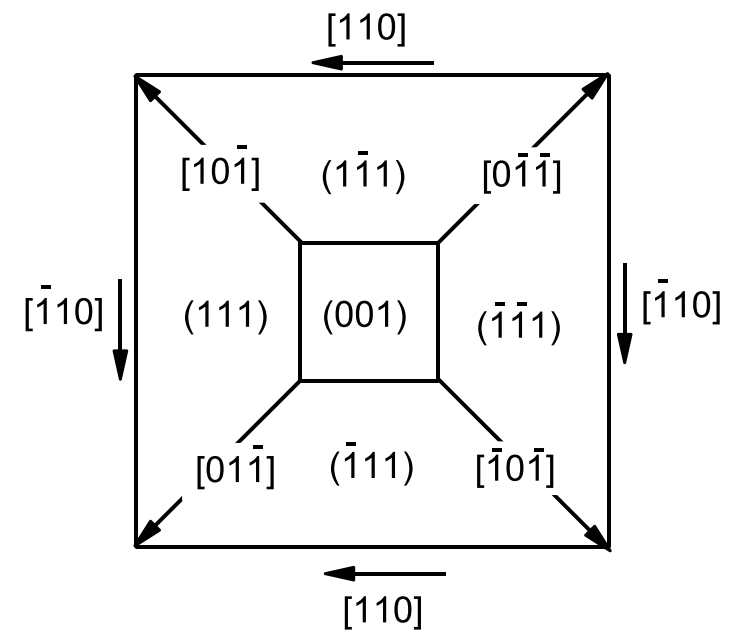
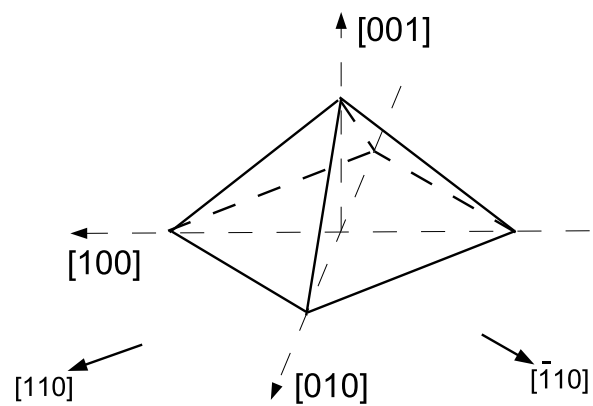
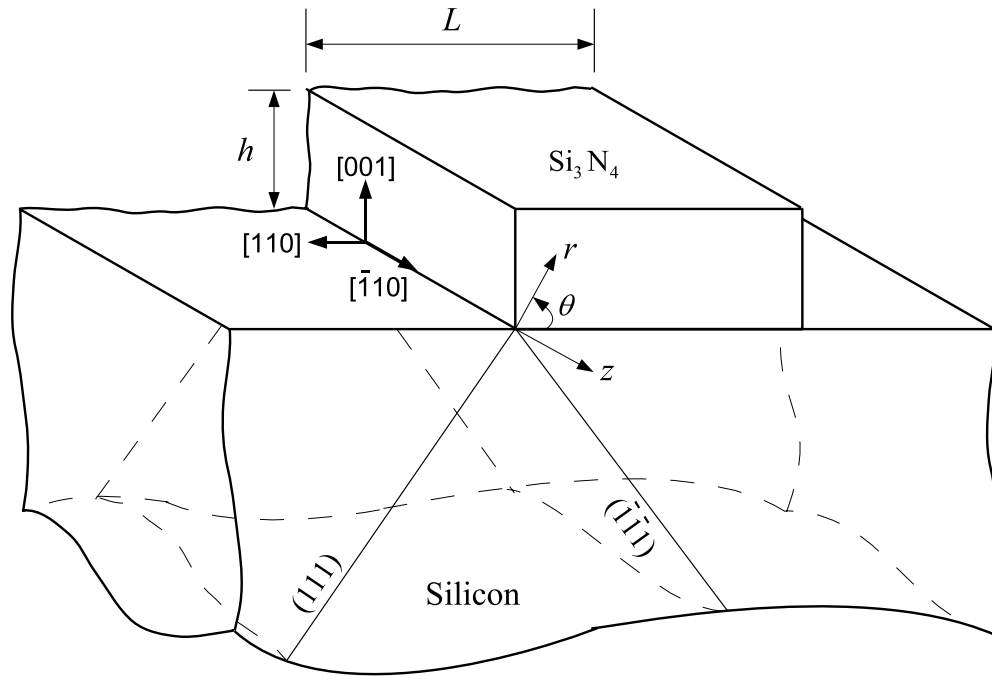
Local mode mixity:

$$\eta = \frac{\kappa_2}{\kappa_1} \left(\frac{b}{h} \right)^{\lambda_1 - \lambda_2}$$

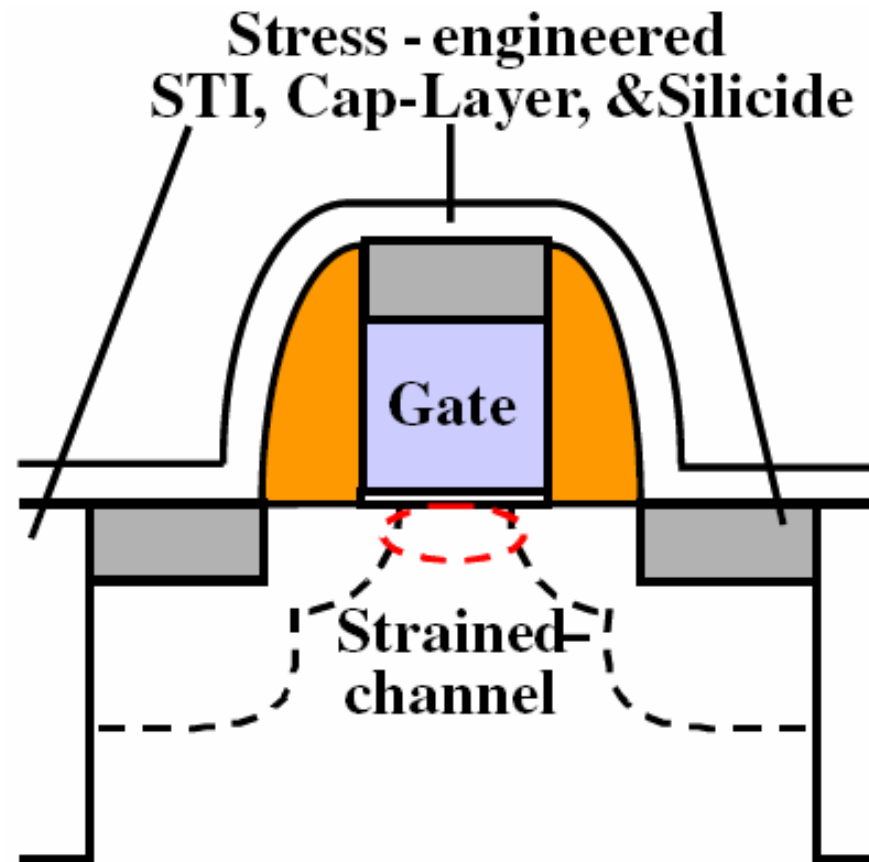


Evaluate it case by case.

Slip systems



Future focus



Ge et al, IEDM 2003.

- Stress driven dislocation motion under channel.