

2D Theory of Elasticity

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Summary

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- Field equations
- Boundary conditions
- Problem formulation
- Plane strain
- Plane stress
- Airy's stress function
- Axially loaded bar
- Pure bending of beam

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Introduction

- In principle all practical problems 3D problems very complex difficult to handle
- Reasonable assumptions bring down the complexity in the problem – reduces a dimension => 2D problem
- 2D problems two independent variables static problem three independent variables dynamic problems
- Field variables, $\phi = \phi(x, y, t)$

Introduction

- Field variable is independent of third dimension => $\frac{\partial \phi}{\partial z}$ = 0
- Continuum approach the following laws hold good
 - Conservation of mass
 - Principle of momentum
 - Principle of moment of momentum
 - First law of thermodynamics
 - Second law of thermodynamics inequality

Introduction

- No inertia effects quasi-static / static
- Small deformation and rotations
- Material => isotropic same properties in all the direction
- Homogeneous material properties are uniform over the domain
- Linear elastic Hooke's law holds good =>
 Hookean material

Field equations

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Strain-displacement equations

$$\mathcal{E}_{ij} = \frac{1}{2} \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right) = \frac{1}{2} \left(u_{i,j} + u_{i,j} \right)$$

Six equation

Compatibility equations

$$\varepsilon_{ij,kl} + \varepsilon_{kl,ij} - \varepsilon_{ik,jl} - \varepsilon_{jl,ik} = 0$$

Six equations – three independent

Field equations

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Equilibrium equations –

$$\sigma_{ij,j} + B_i = 0$$

Three equations

 Constitutive law – Linear elastic – Hooke's law

$$\sigma_{ij} = \lambda \varepsilon_{kk} \delta_{ij} + 2 \mu \varepsilon_{ij}$$

$$\varepsilon_{ij} = \frac{1 + v}{E} \sigma_{ij} - \frac{v}{E} \sigma_{kk} \delta_{ij}$$

Six equations

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Field equations

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- Total 15 equations = 3 Equilibrium +
 6 strain displacement + 6 constitutive laws
- Unknowns => 3 Displacements, 6 stress components and 6 strain components
- Boundary value problem casted as

$$\Im(\underline{u_i, \mathcal{E}_{ij}, \sigma_{ij}, \lambda, \mu, B_i}) = 0$$
Unknowns Lame's constants

Body load

Not easy to solve analytically 15 equations to find out 15 unknowns

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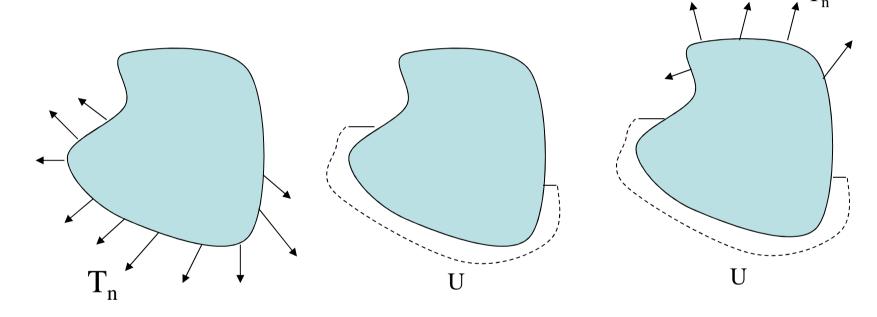


- Solution of a differential (partial) equations –
 boundary conditions required
- Boundary conditions influence the solution –
 field variable in the domain
- BCs play a very essential role for properly formulating and solving elasticity problems
- In elasticity boundary conditions –
 displacements, tractions and combination



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Various boundary conditions in elasticity –



Traction boundary conditions

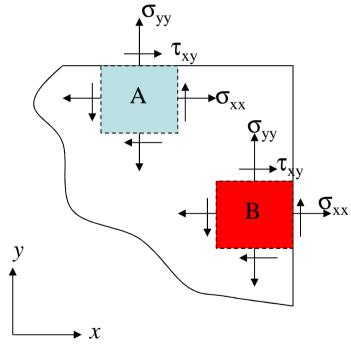
Displacement boundary conditions

Mixed boundary conditions



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Tractions –



$$T_{x} = l \sigma_{xx} + m \tau_{xy}$$

$$T_{y} = l \tau_{xy} + m \sigma_{yy}$$

At 'A' – Direction cosines of area normal \Rightarrow (0, 1, 0)

 σ_{xx} is inside the boundary – this need not be zero

$$T_x = \tau_{xy}; \quad T_y = \sigma_{yy}$$

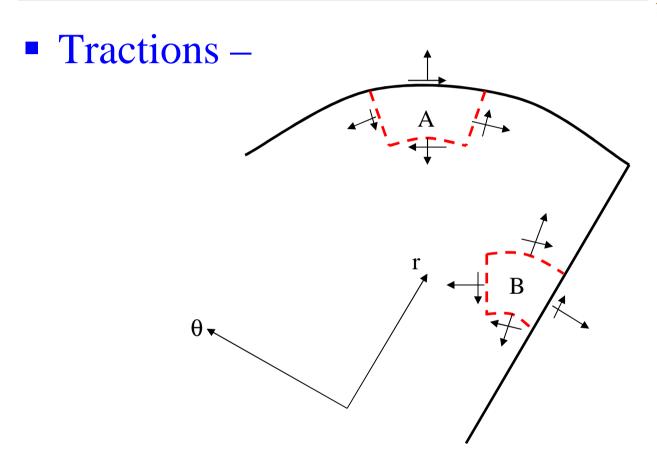
At 'B' – Direction cosines of area normal \Rightarrow (1, 0, 0)

$$T_x = \sigma_{xx}; \, T_y = \tau_{xy}$$

 σ_{yy} is inside the boundary – this need not be zero



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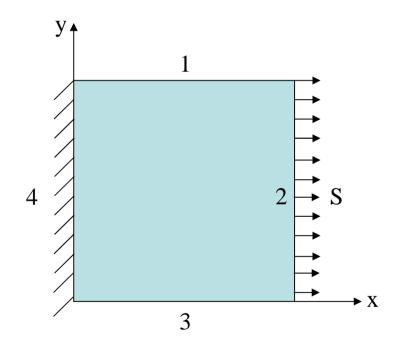


Tractions in Polar co-ordinate system
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Tractions –



Boundary – 4

$$u = 0; v = 0$$

Boundary - 1 – traction free

$$DC => (0, 1, 0)$$

$$T_x = 0. \ \sigma_{xx} + 1. \ \tau_{xy} = 0$$

$$\Rightarrow T_x = \tau_{xy} = 0$$

$$\Rightarrow$$
T_v = 0. τ _{xy} + 1. σ _{yy} = 0 => σ _{yy} = 0

Boundary -2 – DCs (1, 0, 0)

$$T_x = 1. \sigma_{xx} + 0. \tau_{xy} = S = \sigma_{xx}$$

$$T_y = 1. \ \tau_{xy} + 0. \ \sigma_{yy} = 0 = \tau_{xy}$$

Boundary
$$-3$$
 – DCs (0, -1, 0)

$$T_x = 0. \ \sigma_{xx} - 1. \ \tau_{xy} = 0$$

$$T_x = \tau_{xv} = 0$$

$$T_y = 0. \tau_{xy} - 1. \sigma_{yy} = 0 => \sigma_{yy} = 0$$

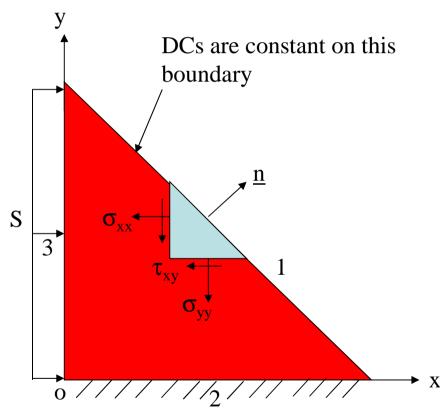
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Tractions



Individual stress components are not zero on boundary - 1

Boundary - 1 – DCs (*l*, *m*, 0)

This is a traction free boundary

$$T_{x} = l\sigma_{xx} + m \tau_{xy} = 0$$

$$T_{y} = m\sigma_{xx} + l \tau_{xy} = 0$$

Boundary -2 – Constrained boundary – U, V = 0

Boundary -3- Traction is acting

$$DCs(-1, 0, 0)$$

$$T_x = -1\sigma_{xx} + m \tau_{xy} = S = > \sigma_{xx} = -S$$

$$T_{y} = m\sigma_{xx} + l \tau_{xy} = 0 \Longrightarrow \tau_{xy} = 0$$



Problem formulation

- 3D elasticity 15 equations and 15 unknowns 2D elasticity 8 equations and 8 unknowns
- Reformulating elasticity problems mathematically convenient way
- Two approaches
 - Displacement based
 - Stress based formulations
- Displacement based express filed equation in terms of displacements, u_i Navier equation
- Stress based express filed equation in terms of stresses, σ_{ij}



Problem formulation

- In displacement based formulation
 - Primary variable displacement solution is obtained for displacements – stresses and strains secondary / derived variables
 - Strains derivation of displacements
 - Stresses use constitutive law
- In stress based formulation
 - Primary variable stresses solution is obtained for stresses – strains and displacements secondary variables
 - Strain compatibility equations

- Governing equation expressed in displacements
- Field equations –

Equilibrium
$$\sigma_{ij,j} + B_i = 0$$
 - (1)

Strain - displacement
$$\varepsilon_{ij} = \frac{1}{2} \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right)$$
 - (2)

Constitutive law
$$\sigma_{ij} = \lambda \varepsilon_{kk} \delta_{ij} + 2\mu \varepsilon_{ij}$$
 - (3)

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Differentiate (3) wrt 'j'

$$\sigma_{ij,j} = \lambda \varepsilon_{kk,j} \delta_{ij} + 2\mu \varepsilon_{ij,j} - (4)$$

Plug this in (1)

$$\sigma_{ij,j} + B_i = \lambda \varepsilon_{kk,j} \delta_{ij} + 2\mu \varepsilon_{ij,j} + B_i = 0 \quad -(5)$$

Express all strain components in (5) in terms of displacements – Use equation (2)

$$\lambda u_{k,kj} \delta_{ij} + \mu (u_{i,jj} + u_{j,ij}) + B_i = 0$$

$$\lambda u_{k,ki} + \mu u_{j,ji} + \mu u_{i,jj} + B_i = 0$$

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$$\lambda u_{k,ki} + \mu u_{j,ji} + \mu u_{i,jj} + B_i = 0$$
$$(\lambda + \mu) u_{j,ji} + \mu u_{i,jj} + B_i = 0$$

This gives three equations for i = 1, 2 and 3

For $i = 1 \Rightarrow x$ - direction

$$(\lambda + \mu) \frac{\partial}{\partial x_1} \left(\frac{\partial u_1}{\partial x_1} + \frac{\partial u_2}{\partial x_2} + \frac{\partial u_3}{\partial x_3} \right) + \mu \left(\frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial x_2^2} + \frac{\partial^2}{\partial x_3^2} \right) u_1 + B_1 = 0$$

Combining all three equations into a single equation

$$(\lambda + \mu) \nabla (\nabla \cdot U) + \mu \nabla^2 U + B = 0$$

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- Governing equations in terms of displacements
 - three equations reduced from '15' equations

$$(\lambda + \mu)u_{j,ji} + \mu u_{i,jj} + B_i = 0 - (U)$$

$$\Im(u_i, \lambda, \mu, B_i) = 0$$
 Navier equation

Equations (U) known as Navier's or Lame's equations

Boundary conditions => $u_i = U_i$ on 'S' boundary $u_i = u_i(x_1, x_2, x_3)$

Solve second order PDEs – get displacements

Use strain – displacement relations for calculating strains

Constitutive relations for stresses

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- In displacement formulation compatibility equations play no role – displacement obtained are single valued and continuous
- In stress formulation express governing equation in terms of stresses
- Stresses primary variables obtain secondary variables displacements from strain-displacement relations
- Integrate ε -U relations compatibility equations come into play

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- Boundary conditions only tractions
- From the filed equations eliminate strains and displacements
- Compatibility equation

$$\mathcal{E}_{ij,kl} + \mathcal{E}_{kl,ij} - \mathcal{E}_{ik,jl} - \mathcal{E}_{jl,ik} = 0 - (1)$$

For k = l first three compatibility equations are obtained

Constitutive law
$$\varepsilon_{ij} = \frac{1+\upsilon}{E} \sigma_{ij} - \frac{\upsilon}{E} \sigma_{kk} \delta_{ij}$$

Differentiate this wrt k and l, plug in (1)

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• Three compatibility equations for k=l=1, 2 and 3

$$\frac{\partial^{2} \varepsilon_{xx}}{\partial y^{2}} + \frac{\partial^{2} \varepsilon_{yy}}{\partial x^{2}} = \frac{\partial^{2} \gamma_{xy}}{\partial x \partial y}$$

$$(i = j = 1, k = l = 2)$$

$$\frac{\partial^{2} \varepsilon_{xx}}{\partial z^{2}} + \frac{\partial^{2} \varepsilon_{zz}}{\partial x^{2}} = \frac{\partial^{2} \gamma_{xz}}{\partial x \partial z}$$

$$(i = j = 3, k = l = 1)$$

$$\frac{\partial^{2} \varepsilon_{yy}}{\partial z^{2}} + \frac{\partial^{2} \varepsilon_{zz}}{\partial y^{2}} = \frac{\partial^{2} \gamma_{yz}}{\partial y \partial z}$$

$$(i = j = 2, k = l = 3)$$



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This gives –

$$\sigma_{ij,kk} + \sigma_{kk,ij} - \sigma_{ik,jk} - \sigma_{jk,ik} =$$

$$\frac{\upsilon}{1+\upsilon}\left(\sigma_{mm,kk}\delta_{ij}+\sigma_{mm,ij}\delta_{kk}-\sigma_{mm,jk}\delta_{ik}-\sigma_{mm,ik}\delta_{jk}\right)$$

$$\delta_{kk} = 3$$

equilibrium eqn.
$$\sigma_{ij,j} + B_i = 0$$

$$\sigma_{ij,j} = -B_i$$

Make use of equilibrium equation to reduce further

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Governing equation in terms of stress –

$$\sigma_{ij,kk} + \frac{1}{1+v}\sigma_{kk,ij} = \frac{v}{1+v}\sigma_{mm,kk}\delta_{ij} - B_{i,j} - B_{j,i}$$

$$\Im(\sigma_{ij}, \lambda, \mu, B_i) = 0$$

Compatibility equation in terms of stresses, known as

"Beltrami-Michell" compatibility equation

Six equations can be obtained for i, j = 1, 2, 3

Only three are independent – similar to strain compatibility equations

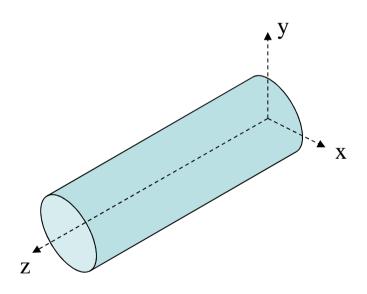
Three more equations are required – complemented by three equilibrium equations - Six unknowns – six equations Ramadas Chennamsetti



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Out-of-plane dimensions are large compared to in-plane dimensions

All loads and boundary conditions



Reduce a 3D problem to 2D problem

All loads and boundary conditions independent of 'z' co-ordinate

The deformation in 'z' direction assumed to be zero. w = 0

Deformations in 'x' and 'y' directions depend on (x, y) only

$$u = u(x, y)$$
 and $v = v(x, y)$

All cross-sections have same displacements

Out of plane strains vanish

- In plane strain $\varepsilon_{zz} = 0$, $\gamma_{yz} = 0$ and $\gamma_{zx} = 0$
- Linear elastic material Hooke's law

$$\sigma_{ij} = \lambda \varepsilon_{kk} \delta_{ij} + 2\mu \varepsilon_{ij}$$

$$\sigma_{xx} = \lambda (\varepsilon_{xx} + \varepsilon_{yy}) + 2\mu \varepsilon_{xx}$$

$$\sigma_{yy} = \lambda (\varepsilon_{xx} + \varepsilon_{yy}) + 2\mu \varepsilon_{yy}$$

$$\sigma_{zz} = \lambda (\varepsilon_{xx} + \varepsilon_{yy})$$

$$\tau_{zz} = \lambda (\varepsilon_{xx} + \varepsilon_{yy})$$

$$\tau_{xy} = 2\mu \varepsilon_{xy} = \mu \gamma_{xy}$$

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Equilibrium equations –

$$\sigma_{ij,j} + B_i = 0$$

$$\frac{\partial \sigma_{xx}}{\partial x} + \frac{\partial \tau_{xy}}{\partial y} + B_x = 0 - (1)$$

$$\frac{\partial \tau_{xy}}{\partial x} + \frac{\partial \sigma_{xx}}{\partial y} + B_y = 0 - (2)$$

Use constitutive law and strain-displacement equations in (1)

$$\frac{\partial}{\partial x} \left(\lambda \left(\varepsilon_{xx} + \varepsilon_{yy} \right) + 2\mu \varepsilon_{xx} \right) + \frac{\partial}{\partial y} \left(\mu \gamma_{xy} \right) + B_i = 0$$

$$\frac{\partial}{\partial x} \left[\lambda \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) + 2\mu \frac{\partial u}{\partial x} \right] + \frac{\partial}{\partial y} \left[\mu \left(\frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} \right) \right] + B_x = 0$$

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Governing equation in x – direction

$$\mu \nabla^2 u + (\lambda + \mu) \frac{\partial}{\partial x} \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) + B_x = 0$$

Use second equilibrium equation – convert to displacements

$$\mu \nabla^2 v + (\lambda + \mu) \frac{\partial}{\partial y} \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) + B_y = 0$$

In each of the above two equations, equilibrium, constitutive law and displacement – strain equations are inbuilt - *Displacement formulation*

Eight equations => reduced to two equations in displacements

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Stress based formulation -

In 2D case, compatibility equation

$$\frac{\partial^2 \varepsilon_{xx}}{\partial y^2} + \frac{\partial^2 \varepsilon_{yy}}{\partial x^2} = \frac{\partial^2 \gamma_{xy}}{\partial x \partial y}$$

Use constitutive law – convert into

stresses

$$\varepsilon_{xx} = \frac{\sigma_{xx}}{E} - \frac{\upsilon}{E} \left(\sigma_{yy} + \sigma_{zz} \right)$$

$$\varepsilon_{yy} = \frac{\sigma_{yy}}{E} - \frac{\upsilon}{E} (\sigma_{xx} + \sigma_{zz})$$

$$\varepsilon_{zz} = 0 = \frac{\sigma_{zz}}{E} - \frac{\upsilon}{E} \left(\sigma_{xx} + \sigma_{yy} \right) => \sigma_{zz} = \upsilon \left(\sigma_{xx} + \sigma_{yy} \right)$$

$$\gamma_{xy} = \frac{2(1+v)}{E} \tau_{xy}$$

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Compatibility equation in terms of stresses

$$\frac{\partial^2}{\partial x^2} \left[(1 - v)\sigma_{yy} - v\sigma_{xx} \right] + \frac{\partial^2}{\partial y^2} \left[(1 - v)\sigma_{xx} - v\sigma_{yy} \right] = 2 \frac{\partial^2 \tau_{xy}}{\partial x \partial y}$$

Above equation is obtained from compatibility, constitutive equations

Use equilibrium equations to eliminate shear stress from above equation

$$\frac{\partial \sigma_{xx}}{\partial x} + \frac{\partial \tau_{xy}}{\partial y} + B_x = 0 \Longrightarrow \frac{\partial}{\partial x} \left(\frac{\partial \sigma_{xx}}{\partial x} + \frac{\partial \tau_{xy}}{\partial y} + B_x \right) = 0$$

$$\frac{\partial \tau_{xy}}{\partial x} + \frac{\partial \sigma_{xx}}{\partial y} + B_y = 0 \Longrightarrow \frac{\partial}{\partial y} \left(\frac{\partial \tau_{xy}}{\partial x} + \frac{\partial \sigma_{yy}}{\partial y} + B_y \right) = 0$$
Add

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This is obtained as –

$$\frac{\partial^2 \sigma_{xx}}{\partial x^2} + \frac{\partial^2 \sigma_{yy}}{\partial y^2} + 2\frac{\partial^2 \tau_{xy}}{\partial x \partial y} + \frac{\partial B_x}{\partial x} + \frac{\partial B_y}{\partial y} = 0$$

$$2\frac{\partial^{2} \tau_{xy}}{\partial x \partial y} = -\left(\frac{\partial^{2} \sigma_{xx}}{\partial x^{2}} + \frac{\partial^{2} \sigma_{yy}}{\partial y^{2}} + \frac{\partial B_{x}}{\partial x} + \frac{\partial B_{y}}{\partial y}\right)$$

$$\frac{\partial^{2}}{\partial x^{2}} \left[(1 - v)\sigma_{yy} - v\sigma_{xx} \right] + \frac{\partial^{2}}{\partial y^{2}} \left[(1 - v)\sigma_{xx} - v\sigma_{yy} \right] = -\left(\frac{\partial^{2}\sigma_{xx}}{\partial x^{2}} + \frac{\partial^{2}\sigma_{yy}}{\partial y^{2}} + \frac{\partial B_{x}}{\partial x} + \frac{\partial B_{y}}{\partial y} \right)$$

Simplifying this expression

$$\nabla^2 \left(\sigma_{xx} + \sigma_{yy} \right) = -\frac{1}{1 - \nu} \left(\frac{\partial B_x}{\partial x} + \frac{\partial B_y}{\partial y} \right)$$
 equation for stress bases formulation of plane strain problems

Single governing equation for stress based strain problems

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Governing equation

$$\nabla^{2} \left(\sigma_{xx} + \sigma_{yy} \right) = -\frac{1}{1 - \upsilon} \left(\frac{\partial B_{x}}{\partial x} + \frac{\partial B_{y}}{\partial y} \right)$$

In this equation, equilibrium, constitutive and compatibility equations are inbuilt.

Three stress components in $2D - \sigma_{xx}$, σ_{yy} , τ_{xx}

Only one governing equation – three unknowns

In 2D two stress equilibrium equations exist – use these two with above governing equation

Boundary conditions given in terms of tractions. Relate them to stresses

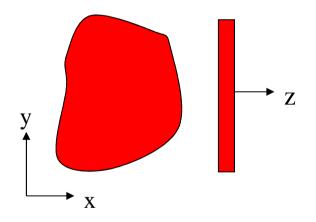
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Plane stress

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■ Third dimension — much smaller than inplane dimensions — Out of plane stresses of T



Thin plates – structures

Reducing a 3D problem to a 2D problem

Out of plane stresses σ_{zz} , τ_{xz} and τ_{yz} negligible

Body can have out of plane deformation

 ε_{zz} is non-zero, γ_{xz} and $\gamma_{yz} = 0$

Stresses are functions of in-plane displacements

$$\sigma_{xx} = \sigma_{xx}(x, y),$$

$$\sigma_{yy} = \sigma_{yy}(x, y),$$

$$\tau_{xy} = \tau_{xy}(x, y)$$

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Plane stress

- Formulation of plane stress problem two approaches
 - Displacement based
 - Stress based approach
- Formulation procedure same as in plane strain
- Formulation takes care of non-zero out of normal strain and zero normal stress
- Use field equations

Plane stress

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Displacement based approach –

$$\begin{cases}
\sigma_{x} \\
\sigma_{y} \\
\tau_{xy}
\end{cases} = \frac{E}{(1-v^{2})} \begin{bmatrix}
1 & v & 0 \\
v & 1 & 0 \\
0 & 0 & \frac{(1-v)}{2}
\end{bmatrix} \begin{cases}
\varepsilon_{x} \\
\varepsilon_{y} \\
\gamma_{xy}
\end{cases} \quad \text{Plug in stress equilibrium equations}$$

$$\frac{\partial \sigma_{xx}}{\partial x} + \frac{\partial \tau_{xy}}{\partial y} + B_{x} = 0; \qquad \frac{\partial \tau_{xy}}{\partial x} + \frac{\partial \sigma_{xx}}{\partial y} + B_{y} = 0$$

$$\frac{\partial}{\partial x} \left[\frac{E}{1-v^{2}} \varepsilon_{xx} + \frac{Ev}{1-v^{2}} \varepsilon_{yy} \right] + \frac{\partial}{\partial y} \left[\frac{E}{2(1+v)} \left(\frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} \right) \right] + B_{x} = 0$$

$$\frac{\partial}{\partial y} \left[\frac{E}{1 - v^2} \varepsilon_{yy} + \frac{Ev}{1 - v^2} \varepsilon_{xx} \right] + \frac{\partial}{\partial x} \left[\frac{E}{2(1 + v)} \left(\frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} \right) \right] + B_y = 0$$

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- Use strain displacement equations to convert strains into displacements
- Governing equations in terms of displacements

$$\mu \nabla^2 u + \frac{E}{2(1-v)} \frac{\partial}{\partial x} \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) + B_x = 0$$

$$\mu \nabla^2 v + \frac{E}{2(1-v)} \frac{\partial}{\partial y} \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) + B_y = 0$$

In the above two equations – equilibrium, constitutive laws and strain-displacements equations



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 Stress based approach – field equations in plane stress problems

Constitutive laws

$$\varepsilon_{xx} = \frac{\sigma_{xx}}{E} - \frac{\upsilon}{E} \sigma_{yy}$$

$$\varepsilon_{yy} = \frac{\sigma_{yy}}{E} - \frac{v}{E}\sigma_{xx}$$

$$\gamma_{xy} = \frac{2(1+\upsilon)}{E} \tau_{xy}$$

Equilibrium equations

$$\frac{\partial \sigma_{xx}}{\partial x} + \frac{\partial \tau_{xy}}{\partial y} + B_x = 0$$

$$\frac{\partial \tau_{xy}}{\partial x} + \frac{\partial \sigma_{xx}}{\partial y} + B_y = 0$$

Compatibility equation

$$\frac{\partial^2 \varepsilon_{xx}}{\partial y^2} + \frac{\partial^2 \varepsilon_{yy}}{\partial x^2} = \frac{\partial^2 \gamma_{xy}}{\partial x \partial y}$$

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- Use constitutive laws in compatibility equation eliminate strains in compatibility using constitutive law
- Compatibility equation in terms of stress stress compatibility equation
- Eliminate shear stress in stress compatibility equation using two equilibrium equations
- Differentiate x direction equilibrium equation wrt 'x' y direction eqn. wrt 'y', add these two get shear stress
- Plug this in stress compatibility equation



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■ The governing equation –

$$\nabla^2 (\sigma_{xx} + \sigma_{yy}) = -(1 + \upsilon) \left(\frac{\partial B_x}{\partial x} + \frac{\partial B_x}{\partial x} \right)$$

This is derived making use of strain compatibility equation, constitutive laws and equilibrium equations



Summary – Plane stress and strain

Formulation	Plane strain	Plane stress
Displacement	$\mu \nabla^2 u + (\lambda + \mu) \frac{\partial}{\partial x} \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) + B_x = 0$	$\mu \nabla^2 u + \frac{E}{2(1-v)} \frac{\partial}{\partial x} \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) + B_x = 0$
	$\mu \nabla^2 v + (\lambda + \mu) \frac{\partial}{\partial y} \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) + B_y = 0$	$\mu \nabla^2 v + \frac{E}{2(1-v)} \frac{\partial}{\partial y} \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) + B_y = 0$
Stress	$\nabla^{2} \left(\sigma_{xx} + \sigma_{yy} \right) = -\frac{1}{1 - v} \left(\frac{\partial B_{x}}{\partial x} + \frac{\partial B_{y}}{\partial y} \right)$	$\nabla^2 (\sigma_{xx} + \sigma_{yy}) = -(1 + \upsilon) \left(\frac{\partial B_x}{\partial x} + \frac{\partial B_x}{\partial x} \right)$



Summary – Plane stress and strain

- Basic difference coefficients involving elastic material constants
- Solving one type of plane problem gives solution to other type also using simple transformation of elastic coefficients
- In absence of body loads in stress formulation governing equations of plane stress and strain are same
 - No elastic constants appear in governing equation
- Solving these equations difficult some text book problems



- In stress based formulation one equation in terms of normal stresses and two equilibrium equations for finding out the complete stress state
- Reduce the complexity of equations
- Introduce a new filed variable 'Airy's stress function' (\$\phi\$)
- Aim reduce the governing equations from three to one
- Find the distribution of single variable 'φ' get stresses from that



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- Airy's stress function (ASF) defined for stress based formulations – both plane stress and plane strain
- Basic stress equilibrium equations –

$$\frac{\partial \sigma_{xx}}{\partial x} + \frac{\partial \tau_{xy}}{\partial y} + B_x = 0 \quad \text{Defining potential}$$

$$\frac{\partial \sigma_{xx}}{\partial x} + \frac{\partial \sigma_{xy}}{\partial y} + B_y = 0 \quad B_x = -\frac{\partial V}{\partial x}, \quad B_y = -\frac{\partial V}{\partial y}$$

$$\frac{\partial \tau_{xy}}{\partial x} + \frac{\partial \sigma_{xx}}{\partial y} + B_y = 0$$

Body loads can be derived from potential function 'V'

$$B = -\nabla V = > B_i = V_{,i}$$

$$B_{x} = -\frac{\partial V}{\partial x}, \quad B_{y} = -\frac{\partial V}{\partial y}$$

Substitute in equilibrium equations



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Equilibrium equations become

$$\frac{\partial}{\partial x}(\sigma_{xx}-V)+\frac{\partial \tau_{xy}}{\partial y}=0; \qquad \frac{\partial \tau_{xy}}{\partial x}+\frac{\partial}{\partial y}(\sigma_{yy}-V)=0$$

Defining ASF as

$$\sigma_{xx} - V = \frac{\partial^2 \phi}{\partial y^2}; \qquad \tau_{xy} = -\frac{\partial^2 \phi}{\partial x \partial y}; \qquad \sigma_{yy} - V = \frac{\partial^2 \phi}{\partial x^2}$$

ASF,
$$\phi = \phi(x, y)$$

ASF satisfies both equilibrium equations.

In stress based formulation – it has to satisfy one more governing equation

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In plane strain – stress based formulation – governing equation

$$\nabla^{2} \left(\sigma_{xx} + \sigma_{yy} \right) = -\frac{1}{1 - \upsilon} \left(\frac{\partial B_{x}}{\partial x} + \frac{\partial B_{y}}{\partial y} \right)$$

$$\nabla^{2} \left(\left(V + \frac{\partial^{2} \phi}{\partial y} \right) + \left(V + \frac{\partial^{2} \phi}{\partial x} \right) \right) = -\frac{1}{1 - \upsilon} \left(\frac{\partial}{\partial x} \left(-\frac{\partial V}{\partial x} \right) + \frac{\partial}{\partial y} \left(-\frac{\partial V}{\partial y} \right) \right)$$

$$\nabla^{2} \left(\frac{\partial^{2} \phi}{\partial x} + \frac{\partial^{2} \phi}{\partial y} \right) + 2\nabla^{2}V = \frac{1}{1 - \upsilon} \nabla^{2}V$$

$$\nabla^{2} \cdot \nabla^{2} \phi = \left(\frac{1}{1 - \upsilon} - 2 \right) \nabla^{2}V$$
Thermonic operator
$$\nabla^{4} \phi = -\left(\frac{1 - 2\upsilon}{1 - \upsilon} \right) \nabla^{2}V$$

Bi-harmonic operator $\nabla^4 \phi = -\left(\frac{1-2\nu}{1-\nu}\right)\nabla^2 V$

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In plane stress – stress based formulation – governing equation

$$\nabla^2 \left(\sigma_{xx} + \sigma_{yy} \right) = -\left(1 + \upsilon \right) \left(\frac{\partial B_x}{\partial x} + \frac{\partial B_y}{\partial y} \right)$$

$$\nabla^{2} \left(\left(V + \frac{\partial^{2} \phi}{\partial y} \right) + \left(V + \frac{\partial^{2} \phi}{\partial x} \right) \right) = -\left(1 + \upsilon \right) \left(\frac{\partial}{\partial x} \left(-\frac{\partial V}{\partial x} \right) + \frac{\partial}{\partial y} \left(-\frac{\partial V}{\partial y} \right) \right)$$

$$\nabla^2 \left(\frac{\partial^2 \phi}{\partial x} + \frac{\partial^2 \phi}{\partial y} \right) + 2\nabla^2 V = (1 + \upsilon)\nabla^2 V$$

$$\nabla^2 \cdot \nabla^2 \phi = (1 + \upsilon - 2) \nabla^2 V$$

$$\nabla^4 \phi = -(1 - \upsilon)\nabla^2 V$$

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Governing equations in terms of ASF

$$\nabla^4 \phi = -\left(\frac{1-2v}{1-v}\right) \nabla^2 V$$
 Plane strain
$$\nabla^4 \phi = -(1-v) \nabla^2 V$$
 Plane stress

If body forces are neglected -V = 0 – In both cases the governing equation is same

$$\nabla^4 \phi = 0 \Longrightarrow \frac{\partial^4 \phi}{\partial x^4} + 2 \frac{\partial^4 \phi}{\partial x^2 \partial y^2} + \frac{\partial^4 \phi}{\partial y^4} = 0$$

Bi-harmonic equation – solution to this equation => ASF

Problem of elasticity reduced to a single equation – find ϕ in solution domain and boundaries – BCs - Tractions

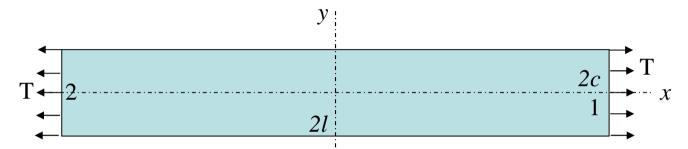


Stress formulation

- This formulation is appropriate for use with traction boundary conditions
- Use Hooke's law for calculating strains from stresses
- Compute displacements from strain-displacement relations
- Since compatibility equations are used in formulating governing equations, the displacements obtained from integration of strain-displacement equations yield single valued, continuous filed
- All equations are used for solving the problem
- Closed form analytical solutions for elasticity problems – difficult – rely on numerical methods

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A bar subjected to tension



Boundary – 1

$$DCs => (1, 0, 0)$$

$$T_x = T = l\sigma_{xx} + m \tau_{xy} = \sigma_{xx} = T$$

$$T_{y} = 0 = m\sigma_{yy} + l \tau_{xy} = > \tau_{xy} = 0$$

Boundary -2

$$DCs => (-1, 0, 0)$$

$$T_{x} = -T = l\sigma_{xx} + m \tau_{xy} = \sigma_{xx} = T$$

$$T_{y} = 0 = m\sigma_{yy} + l \tau_{xy} = > \tau_{xy} = 0$$

Remaining boundaries – stress free.

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Stress in x – direction given by ASF

$$\sigma_{xx} = \text{constant} = \frac{\partial^2 \phi}{\partial y^2} = T \implies \phi = \frac{1}{2}Ty^2 + c_1y + c_2$$
At $x = \pm l$, σ_{yy} and $\tau_{xy} = 0$

$$\varepsilon_{x} = \frac{\sigma_{x}}{E} - \frac{v}{E}\sigma_{y} = \frac{\partial u}{\partial x} = \frac{T}{E} \quad - \quad (1)$$

$$\varepsilon_{y} = \frac{\sigma_{y}}{E} - \frac{\upsilon}{E} \sigma_{x} = \frac{\partial \upsilon}{\partial y} = -\frac{\upsilon T}{E} \quad - \quad (2)$$

Integrate (1) and (2)
$$u = \frac{T}{E}x + f(y)$$
 $f(y)$ and $g(x) - \frac{vT}{E}y + g(x)$ arbitrary functions.

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$$f(y)$$
 and $g(x)$ — arbitrary functions

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Shear strain,

$$\gamma_{xy} = \frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} = \frac{\tau_{xy}}{G} = 0$$

$$\Rightarrow f'(y) + g'(x) = 0$$

$$\Rightarrow -f'(y) = g'(x) = \omega_o$$

$$\Rightarrow \frac{\partial f}{\partial y} = -\omega_o \Rightarrow f = -\omega_o y + u_o$$

$$\frac{\partial g}{\partial x} = \omega_o \Rightarrow g = \omega_o x + v_o$$

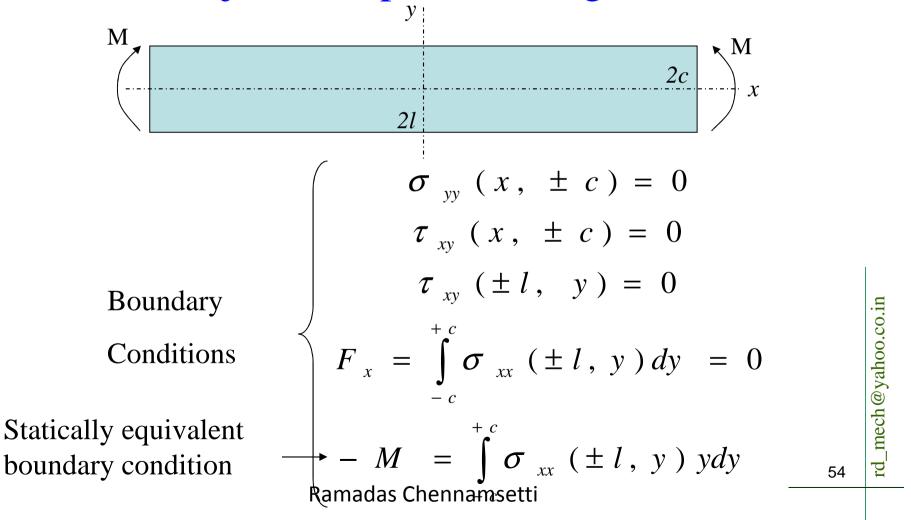
 ω_o , u_o , v_o – arbitrary constants of integration.



- Functions 'f' and 'g' represent rigid body motions
- Rigid body rotation ω_o and translations in 'x' and 'y' directions => u_o and v_o
- Terms related to rigid body motion result from straindisplacement relations
- Displacements are determined from strain fields only up to an arbitrary rigid motion
- For complete determination of displacement filed additional boundary conditions required evaluate ω_o , u_o and v_o
- If rod has no rigid body motion $=> \omega_o$, u_o and $v_o = 0$

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Beam subjected to pure bending –





- Key point in ASF approach selection of an appropriate stress function φ
- It has to satisfy all boundary conditions –
 capture physics of the problem
- Some knowledge about structure's behavior helps in selection of 'φ'
 - In bending, variation of bending stress is linear along 'y' co-ordinate
 - '\phi' should be a cubic polynomial

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Linear variation of bending stress

$$\sigma_{xx} = Ay = \frac{\partial^2 \phi}{\partial y^2}$$
 Integrating the function

$$\phi = \frac{A}{6} y^3 + C_1 y + C_2$$
 ASF satisfies all BCs

$$\int_{-c}^{+c} \sigma_{xx}(\pm l, y) y dy = -M$$

$$\int_{-c}^{+c} Ay^2 dy = -M \implies -A \left(\frac{y^3}{3}\right)_{-c}^{+c} = M \implies A = -\frac{3}{2} \frac{M}{c^3}$$

$$\phi = -\frac{3}{2} \frac{M}{c^3} \frac{y^3}{6} + C_1 y + C_2 = -\frac{M}{4c^3} y^3 + C_1 y + C_2$$

Stresses and strains

$$\phi = -\frac{M}{4c^3} y^3 + C_1 y + C_2 \Rightarrow \sigma_{xx} = \frac{\partial^2 \phi}{\partial y^2} = -\frac{3M}{2c^3} y$$

$$\sigma_{yy} = 0, \quad \tau_{xy} = 0$$

$$\varepsilon_{xx} = \frac{\sigma_{xx}}{E} - v \frac{\sigma_{yy}}{E} \Rightarrow \frac{\partial u}{\partial x} = -\frac{3}{2} \frac{M}{Ec^3} y$$
Integrate strain – displacement equations
$$\varepsilon_{yy} = \frac{\sigma_{yy}}{E} - v \frac{\sigma_{xx}}{E} = \frac{3}{2} \frac{Mv}{Ec^3} y$$
equations

$$u = -\frac{3M}{2Ec^3}xy + f(y);$$
 $v = \frac{3Mv}{4Ec^3}y^2 + g(x)$

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Shear strain

$$\gamma_{xy} = \frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} = 0 \Longrightarrow -\frac{3M}{2Ec^3}x + f'(y) + g'(x) = 0$$

$$\Rightarrow -\frac{3M}{2Ec^3}x + g'(x) = -f'(y) = \omega_o$$
 Integrate

$$g(x) = \frac{3M}{2Ec^3} \frac{x^2}{2} + \omega_o x + v_o$$
$$f(y) = -\omega_o y + u_o$$

Functions g(x) and f(y) represent rigid body motions

To evaluate constants, ω_o , u_o , v_o – constraints required



